

***Pavel Simacek***

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# **MODELING AND SIMULATION OF MOLD FILLING WITH LIMS**

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***UD-CCM***

Report Documentation Page				Form Approved OMB No. 0704-0188	
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1. REPORT DATE <b>26 AUG 2004</b>		2. REPORT TYPE <b>N/A</b>		3. DATES COVERED <b>-</b>	
4. TITLE AND SUBTITLE <b>Modeling And Simulation Of Mold Filling Processes</b>				5a. CONTRACT NUMBER	
				5b. GRANT NUMBER	
				5c. PROGRAM ELEMENT NUMBER	
6. AUTHOR(S)				5d. PROJECT NUMBER	
				5e. TASK NUMBER	
				5f. WORK UNIT NUMBER	
7. PERFORMING ORGANIZATION NAME(S) AND ADDRESS(ES) <b>University of Delaware Center for Composite Materials Newark, DE 19716</b>				8. PERFORMING ORGANIZATION REPORT NUMBER	
9. SPONSORING/MONITORING AGENCY NAME(S) AND ADDRESS(ES)				10. SPONSOR/MONITOR'S ACRONYM(S)	
				11. SPONSOR/MONITOR'S REPORT NUMBER(S)	
12. DISTRIBUTION/AVAILABILITY STATEMENT <b>Approved for public release, distribution unlimited</b>					
13. SUPPLEMENTARY NOTES <b>See also ADM001700, Advanced Materials Intelligent Processing Center: Phase IV., The original document contains color images.</b>					
14. ABSTRACT					
15. SUBJECT TERMS					
16. SECURITY CLASSIFICATION OF:			17. LIMITATION OF ABSTRACT <b>UU</b>	18. NUMBER OF PAGES <b>55</b>	19a. NAME OF RESPONSIBLE PERSON
a. REPORT <b>unclassified</b>	b. ABSTRACT <b>unclassified</b>	c. THIS PAGE <b>unclassified</b>			

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# Outline

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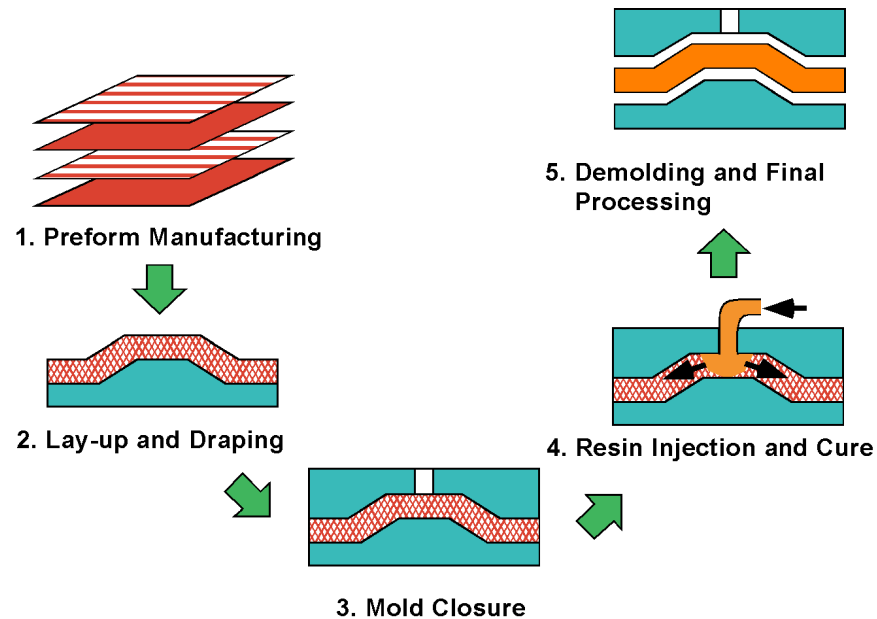


- **What is the Computer Simulation (Modeling)**
- **Why Do We Need Simulation**
- **Computer Modeling - Basics:**
  - ✦ **Experimental Characterization**
  - ✦ **Process Modeling**
    - ✧ Analytic
    - ✧ Numeric
- **Computer Modeling - Advanced:**
  - ✦ **Control and Sensing**
  - ✦ **Optimization**
- **Putting the Whole Package Together or the Art of Integration**
- **Conclusions**

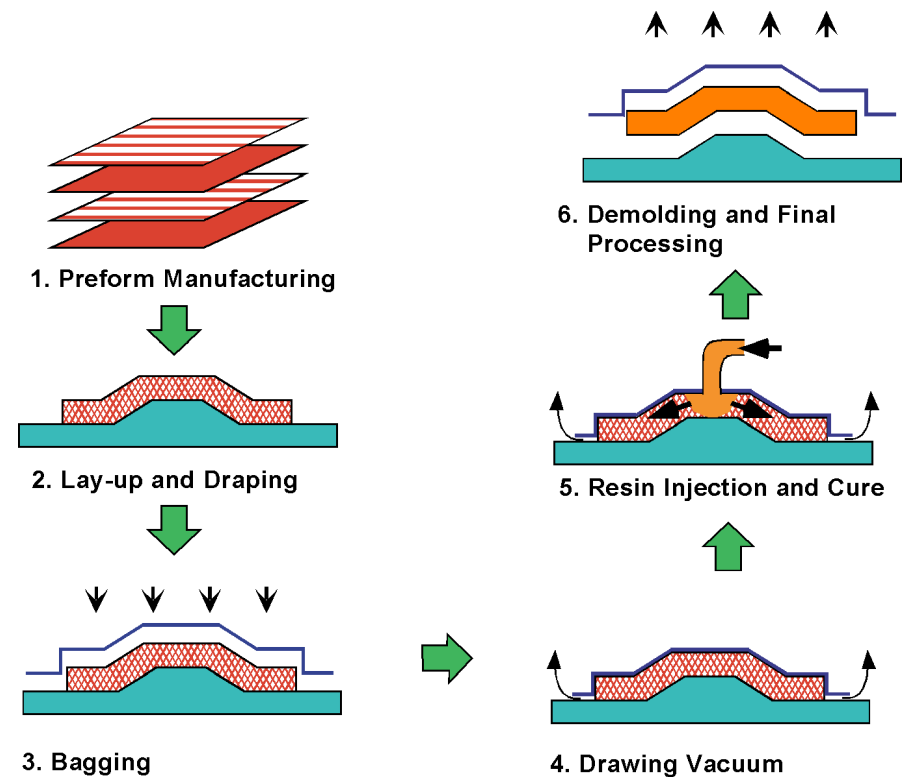
# RTM and VARTM Processes



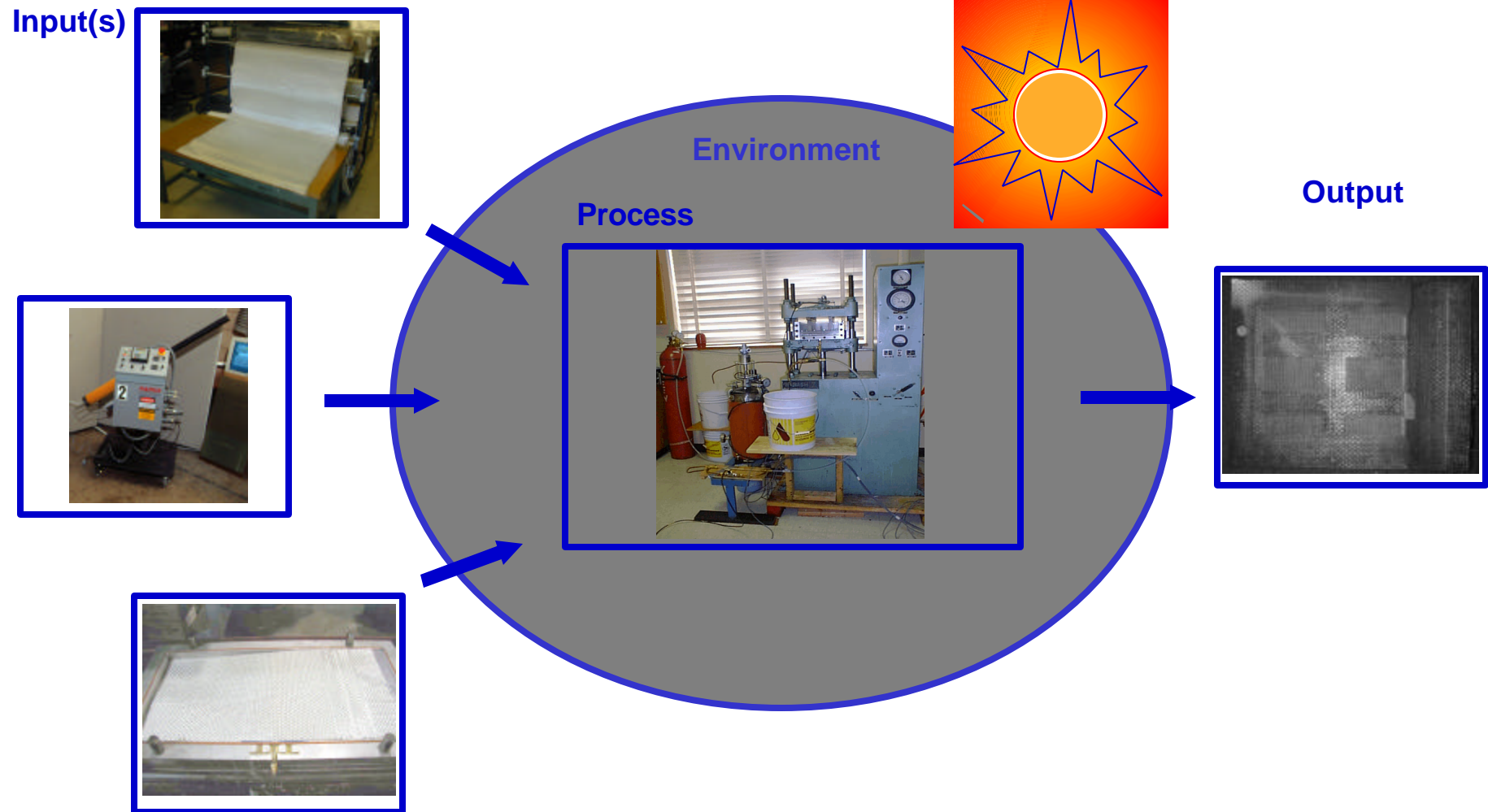
## RTM



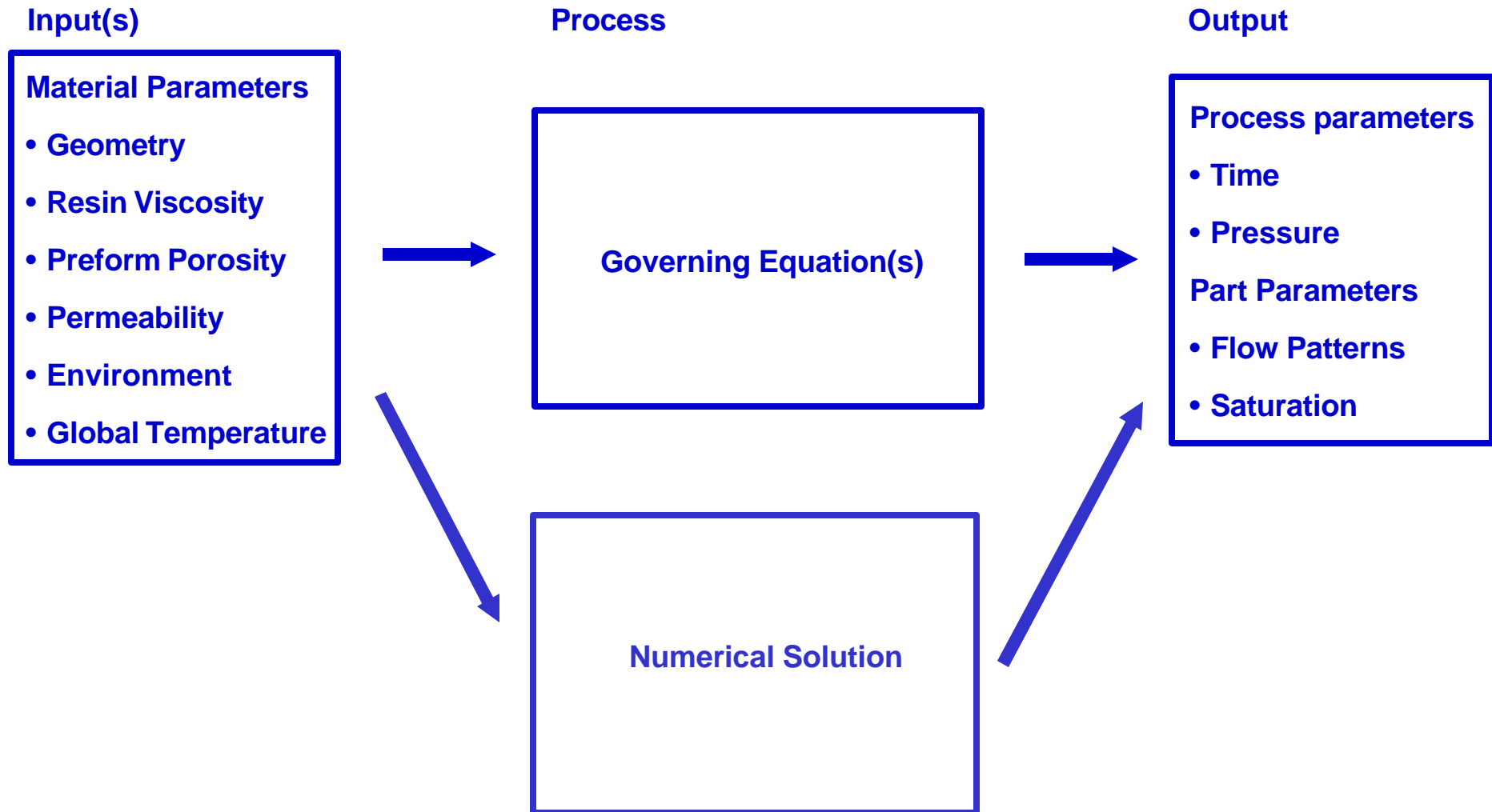
## VARTM



# What Is To Be Simulated?



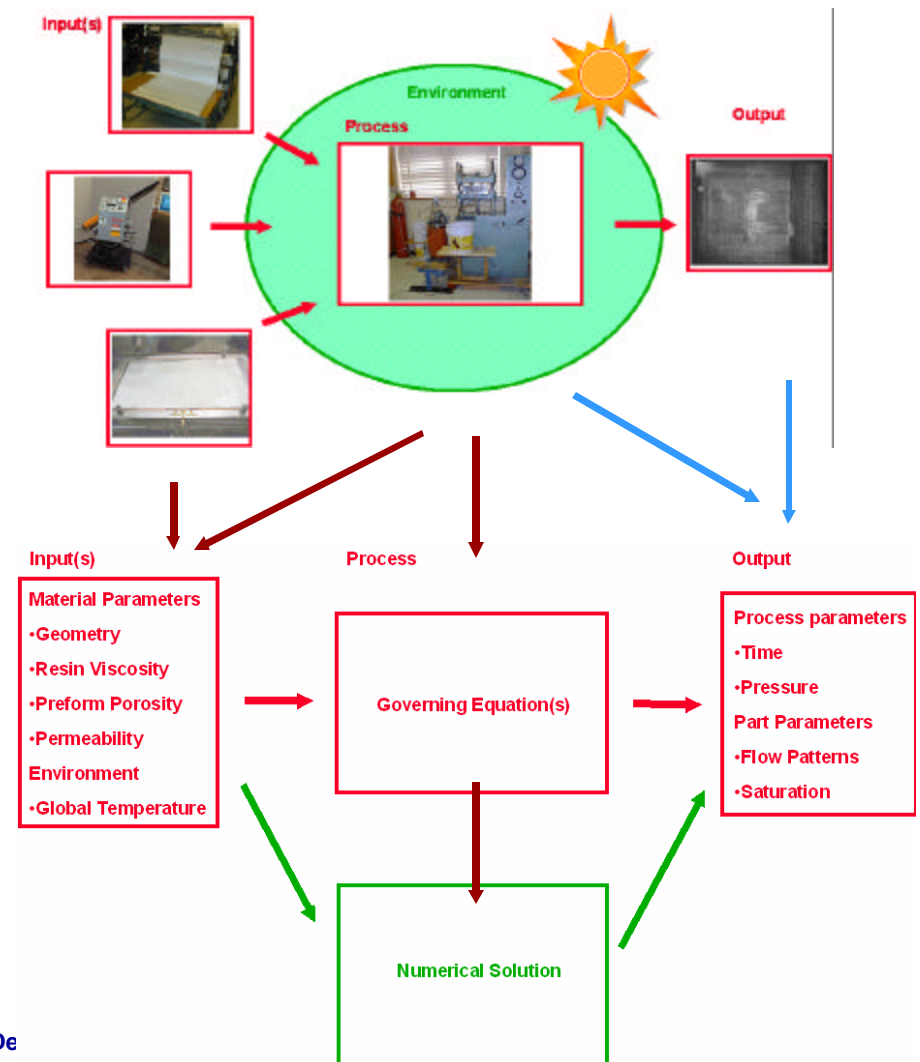
# The Model



# Model Creation

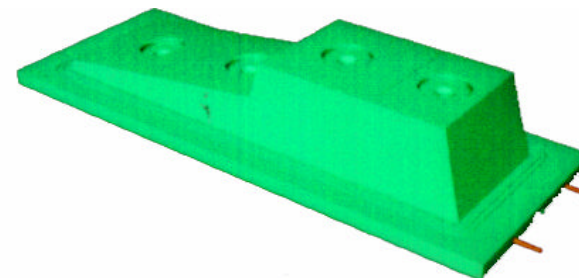
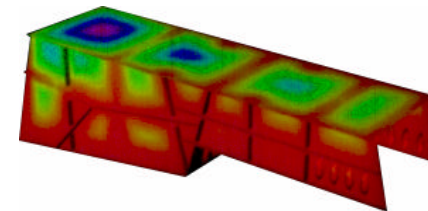
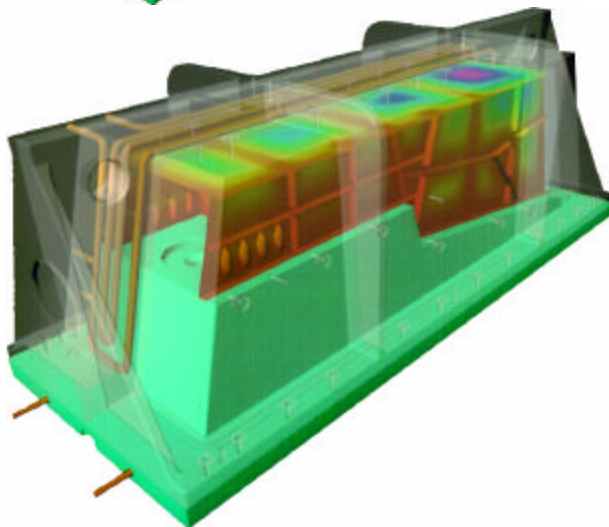
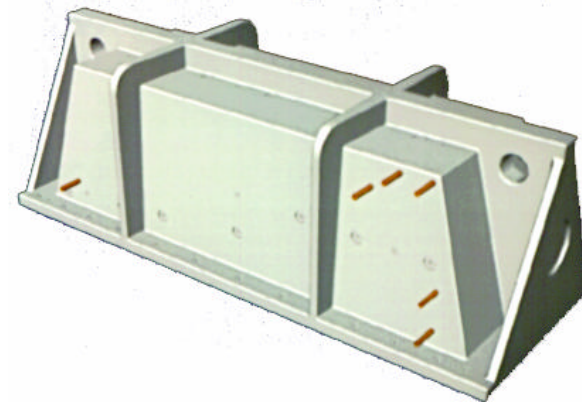
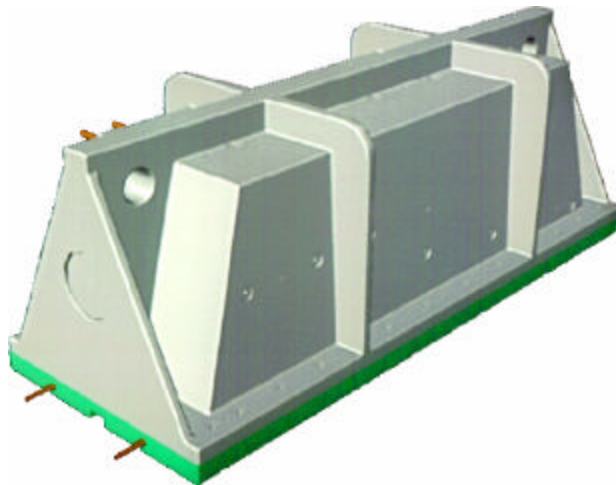


- Choose the output of interest
  - ◆ Decide the accuracy
- Figure out the governing equations
  - ◆ Decide of what is important
  - ◆ Decide of what input and environment parameters are considered
- Solve the equations
  - ◆ Numerical solution
- Number of Sources of Error
  - ◆ Mathematicians mislead!





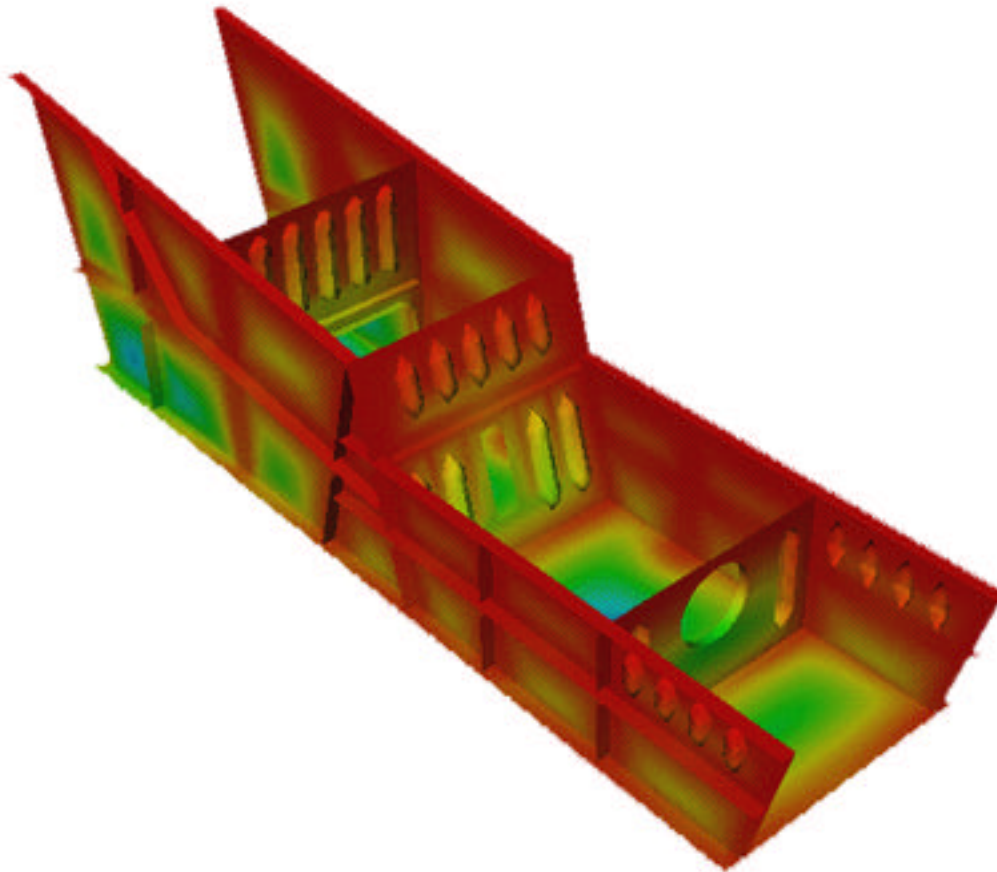
# Keel Beam And Tooling



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# Flow Fronts in a 40-ft. Keel Beam

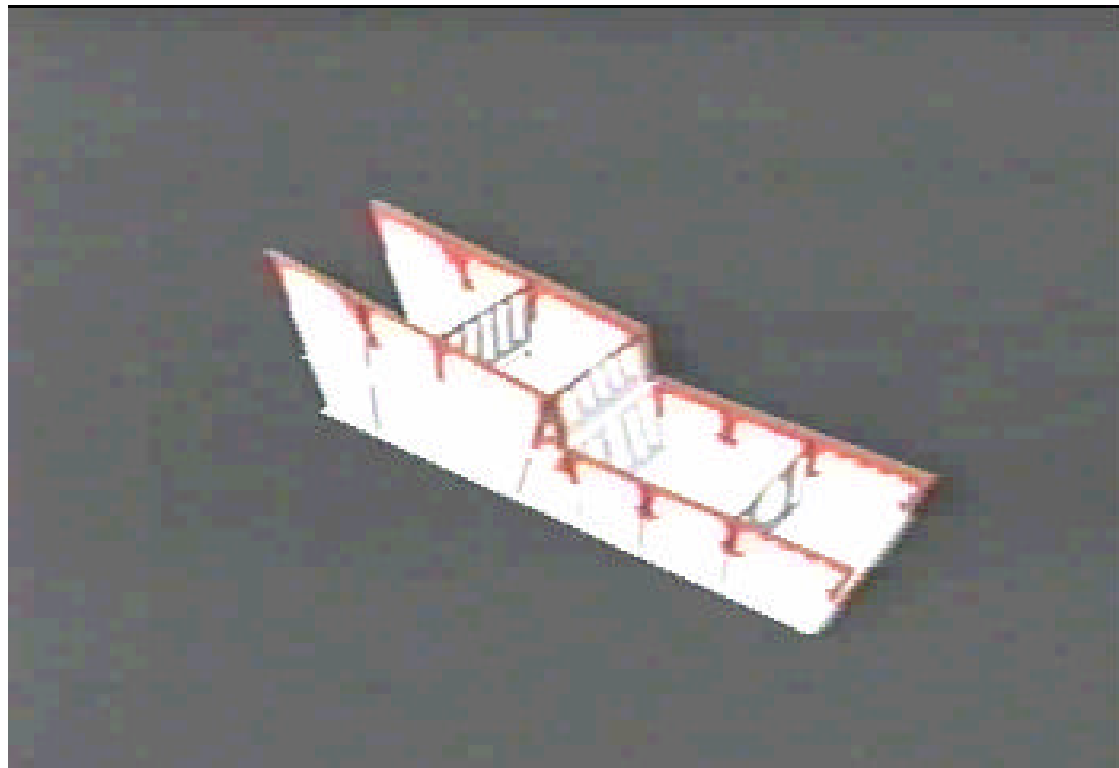
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# Flow Fronts in a 40 ft Keel Beam

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# Why Do We Need Simulation Tools?

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**Can We See Into the Mold?**

**Can We Measure What is Happening?**

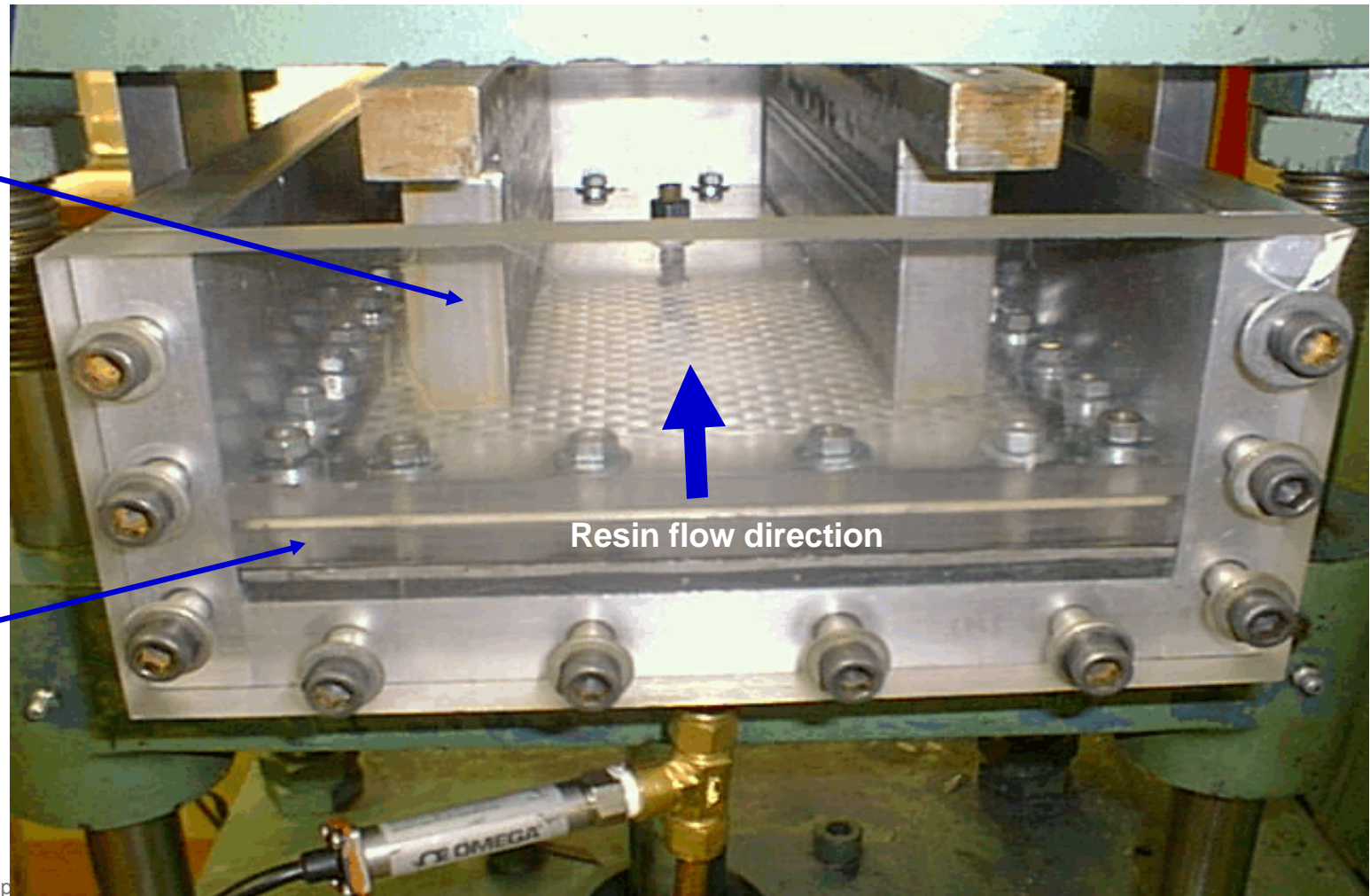
**If We Could, How Much Good Can Come Out Of It?**

# Can We See The Flowfront?



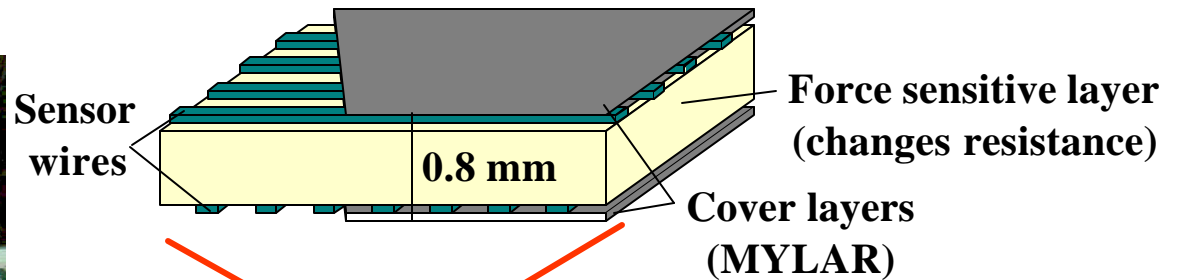
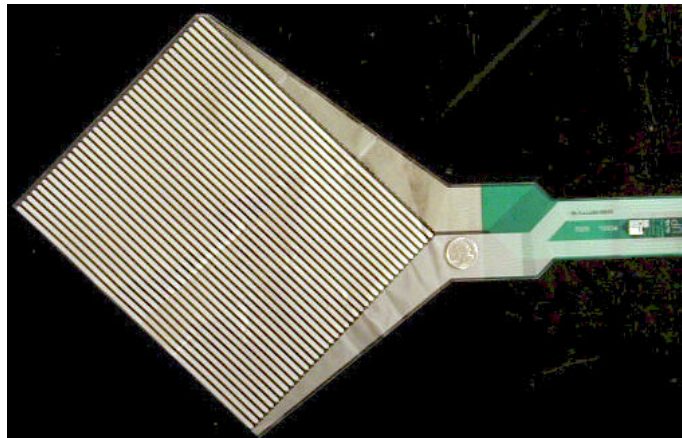
Stiffening bars

Squeezed rubber





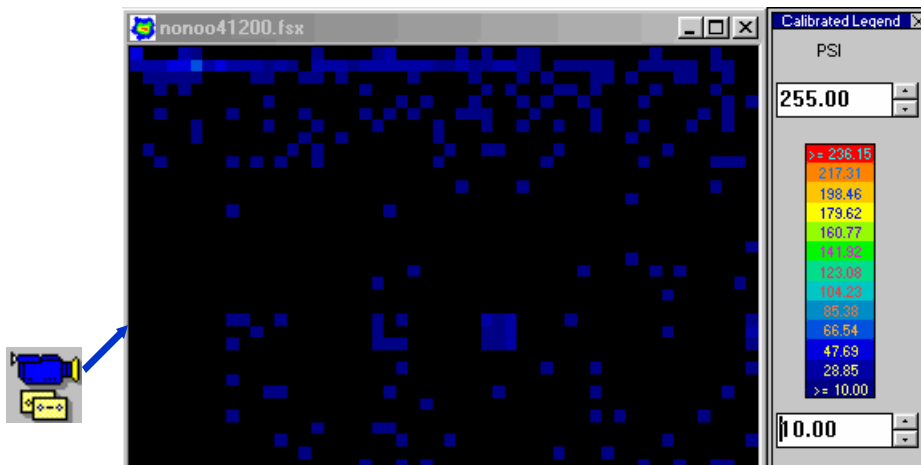
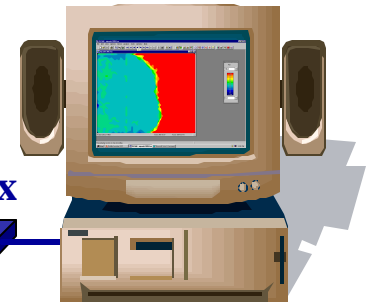
# Can We 'Measure' it?



Flexible  
Tekscan  
sensor

Handle

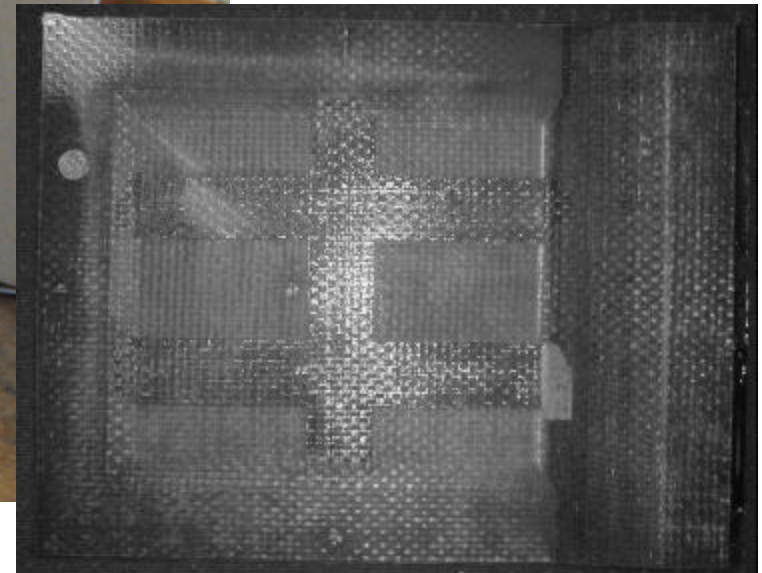
Serial  
interface box



# In Order to Obtain Visual Input, You Must Have:



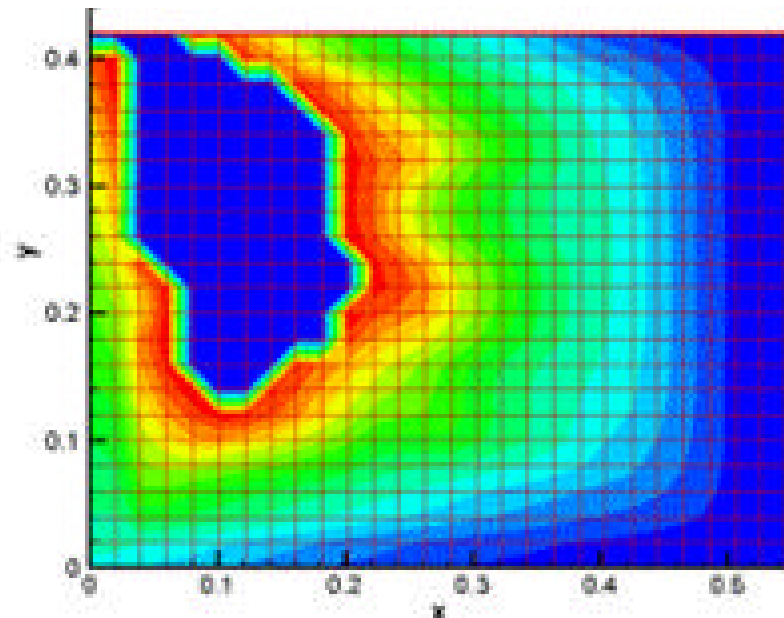
To Get:



# In Order to Obtain Input From Simulation, You Need:



To Get:





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# Why Do We Need Simulation Tools?

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- **Can We See Into the Mold?**
  - ◆ In RTM Manufacturing NO!
  - ◆ In VARTM or Laboratory A little
- **Can We Measure What is Happening?**
  - ◆ Yes, but at High Cost. On Top, the Used Technology is Immature.
- **If We Could, How Much Good Can Come Out Of It?**
  - ◆ Visual/Sensorial Examination Requires Mold and Part to Be Real
  - ◆ Errors -> Post Mortem Analysis -> New Trial
- **PREDICTIVE CAPABILITY IS NEEDED!**

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# What Is Needed for Modeling

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## ➤ **Computer Modeling Basics:**

- ◆ **Experimental Characterization of Used Materials.**
- ◆ **Process Modeling - Equations and Their Solution.**
  - ✧ Analytic.
  - ✧ Numeric.
- ◆ **Tricks of the Trade.**

## ➤ **Computer Modeling Advanced:**

- ◆ **Modeling Control and Sensing and “Intelligent” Manufacturing Processes.**
- ◆ **Process Optimization.**

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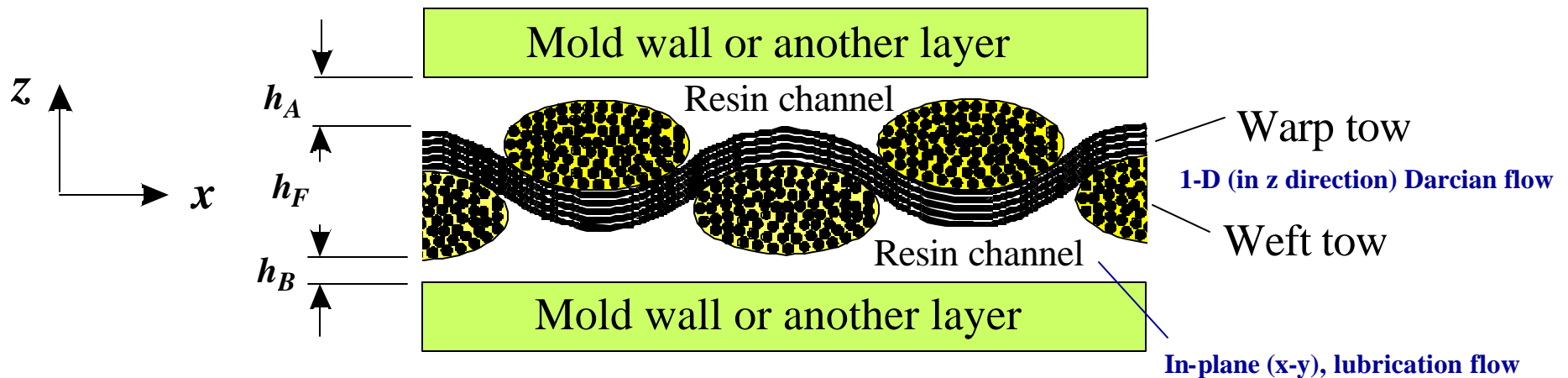
# Lesson I. : Knowing the Material

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- **Characterization of Materials**
  - ◆ **Resins**
  - ◆ **Preforms**
- **Preform Data that Influence the Process**
  - ◆ **Permeability**
  - ◆ **Porosity**
  - ◆ **Thermal Characteristics**
- **Ways to Obtain Them**
  - ◆ **Computer Simulations (Hypothetic)**
  - ◆ **Experimental**
- **Other Uses of Experiment**
  - ◆ **Verification!**

# Numerical Permeability Prediction



$$-\frac{K_{zz}(p^B - p^A)}{hh^F} - \frac{1}{6h} \left( \frac{\partial((h^A)^3 \partial p^A / \partial x)}{\partial x} + \frac{\partial((h^A)^3 \partial p^A / \partial y)}{\partial y} \right) = 0$$

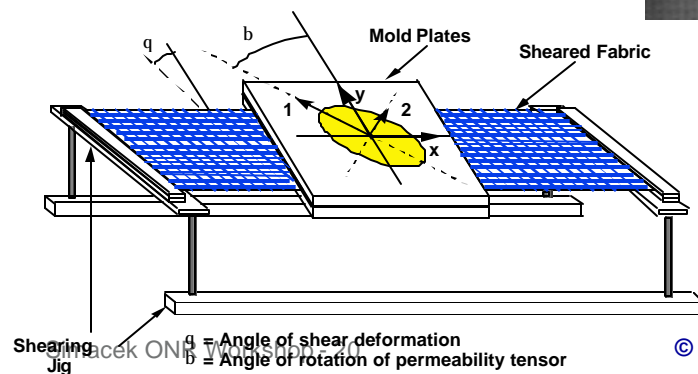
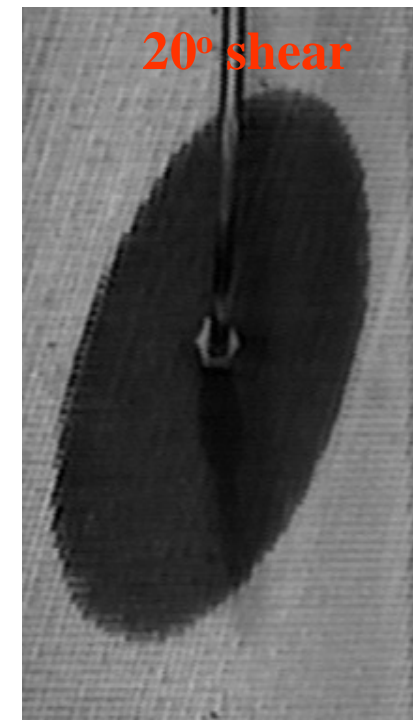
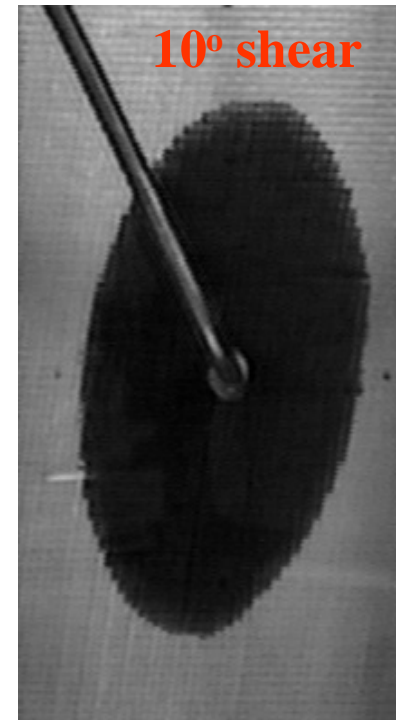
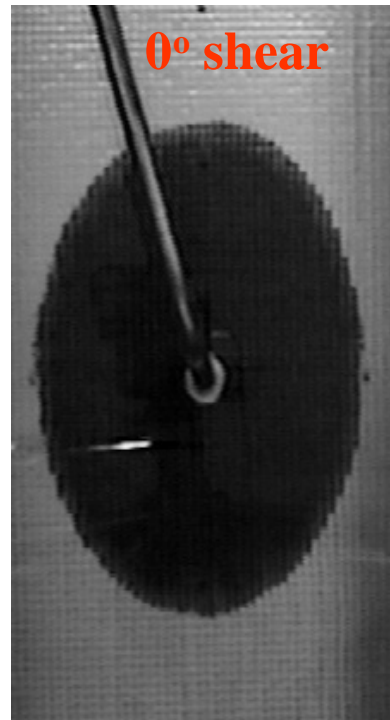
$$\frac{K_{zz}(p^B - p^A)}{hh^F} - \frac{1}{6h} \left( \frac{\partial((h^B)^3 \partial p^B / \partial x)}{\partial x} + \frac{\partial((h^B)^3 \partial p^B / \partial y)}{\partial y} \right) = 0$$

**Input to model:** geometry:  $h_A(x, y), h_F(x, y), h_B(x, y)$

**Output:**  $K_{xx}, K_{yy}, K_{xy}$

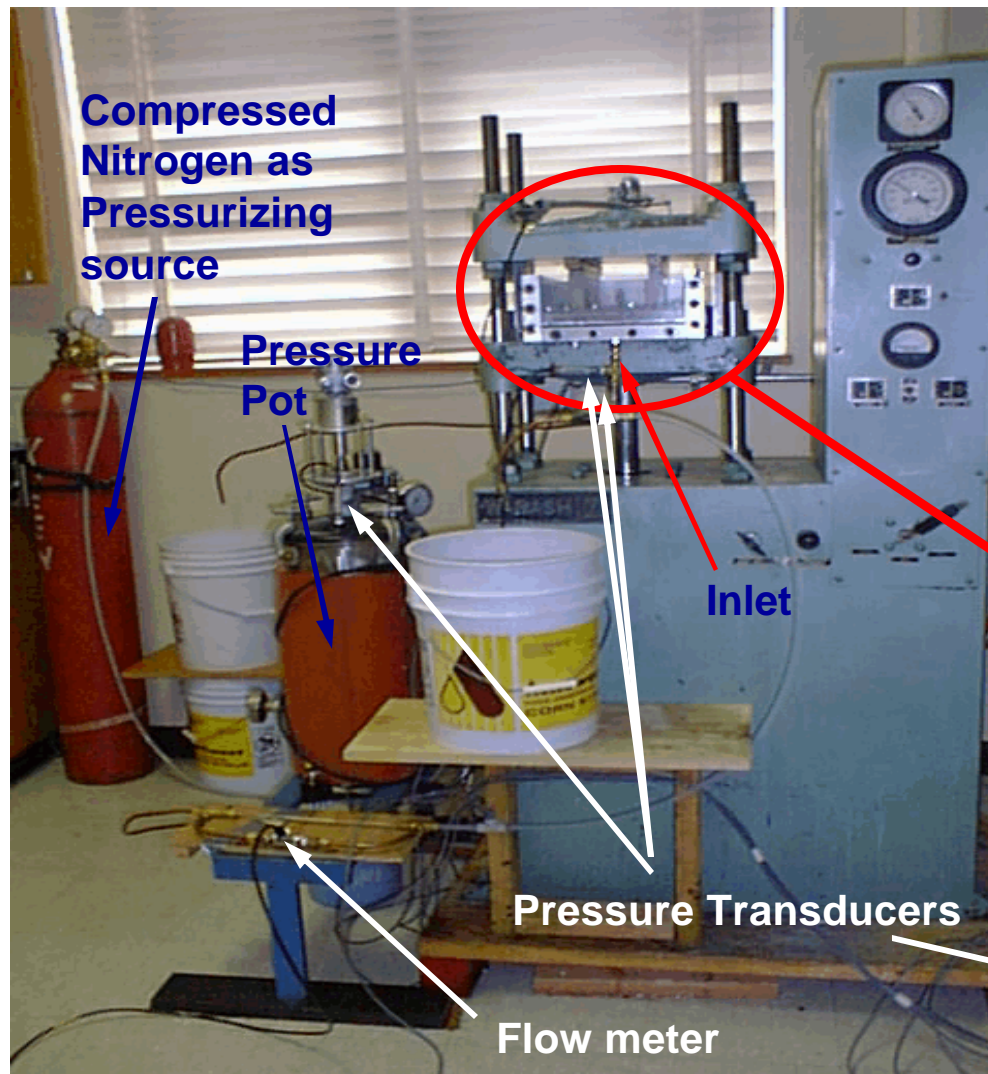
transverse permeability:  $K_{zz}$

# Experimental Permeability Prediction



**Problem: Many Experiments**

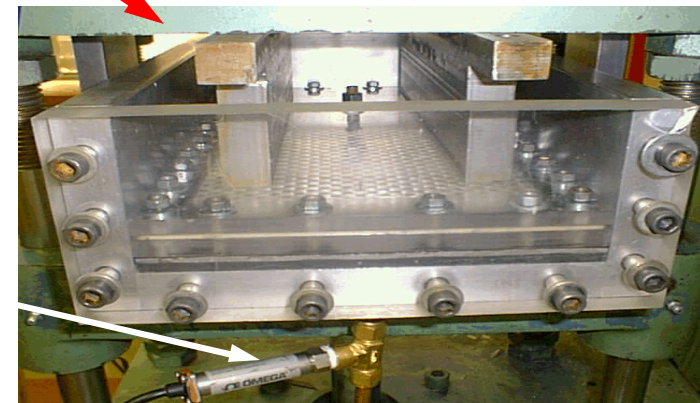
# Permeability vs. $V_f$ Measurement



- ◆ Detailed measurements of permeability vs.  $V_f$  by changing the compaction load

- ◆ Steady state 1-D flow

Experiments were performed by Mats Erninger

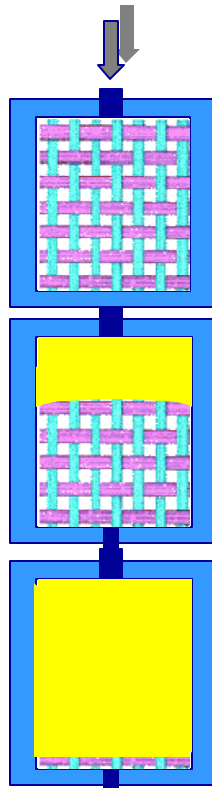




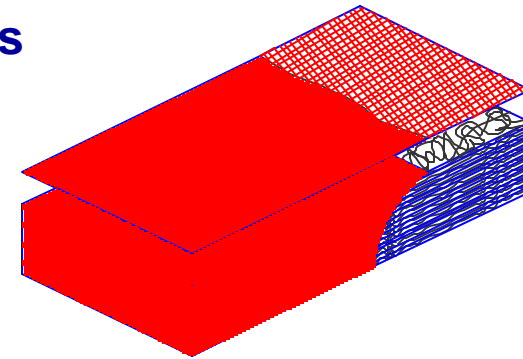
# VARTM Specific Measurement : Distribution Media



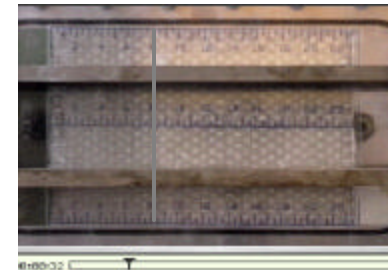
Direct (1D)



Heterogenous Porous  
Media Approach



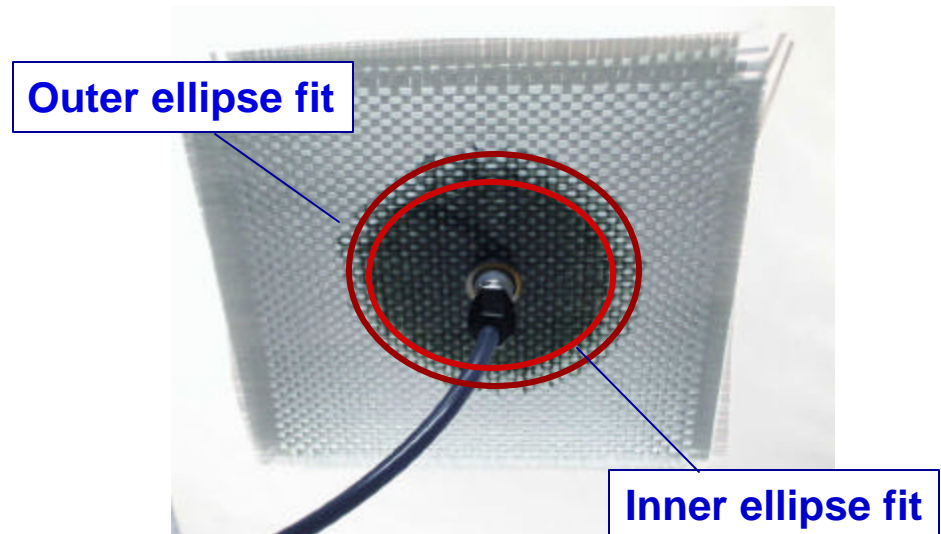
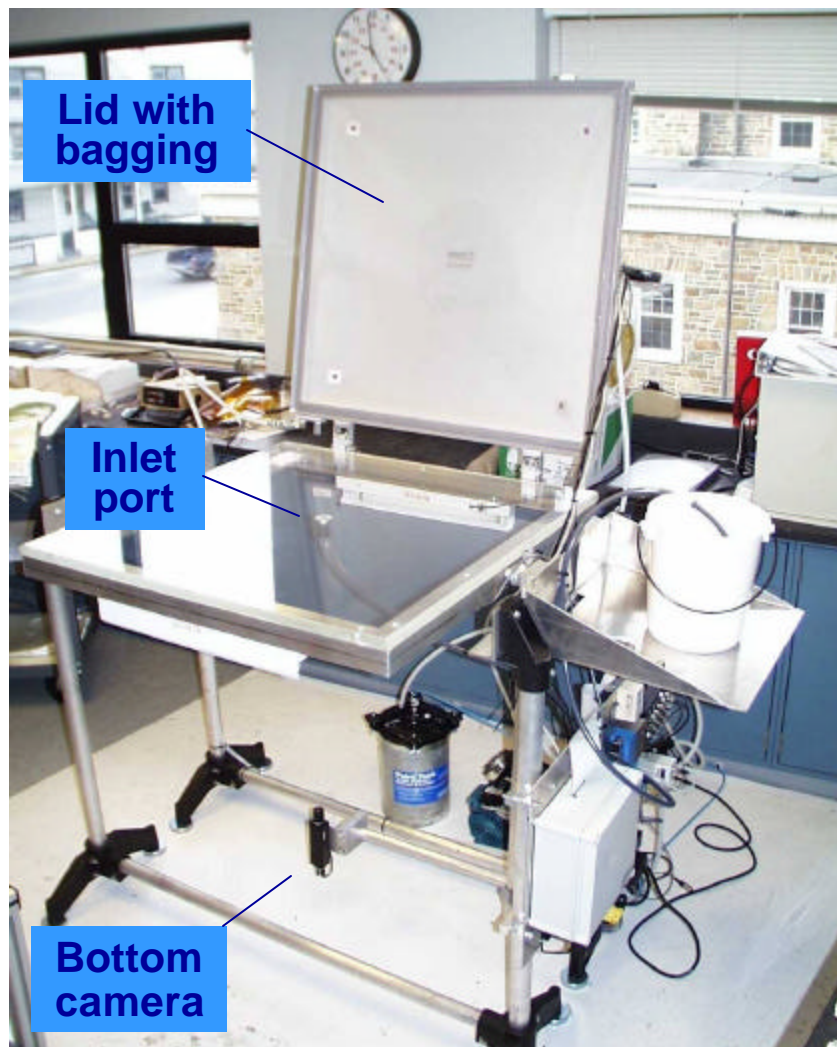
Distribution  
Media



Structural  
layer



# VARTM Specific Measurement : Transverse Permeability

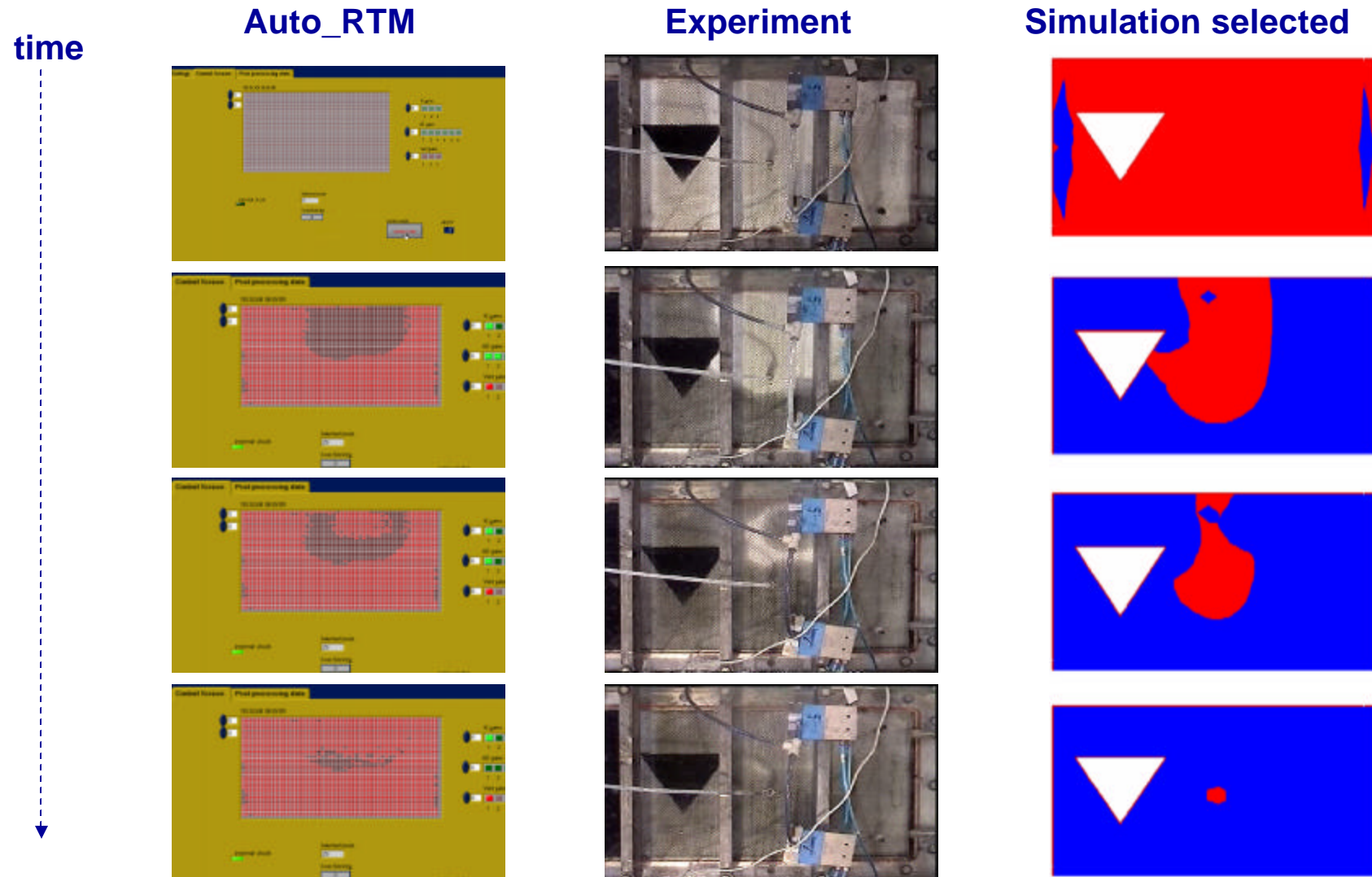


**Top:** Bottom view of point injection into dry preform, with blackened corn syrup

**Left:** PERMSTAT set-up



# Experimental Validation of TekScan Sensor and Flow



# Lesson II. : Describe and Model the Process



## ➤ Equations Dependent on Measured (or Predicted) Data

### ◆ Darcy's Equation

$$\langle \mathbf{v} \rangle = -\frac{\mathbf{K}}{h} \cdot \nabla p$$

### ◆ Continuity Equation

## ➤ Boundary Conditions (More Data)

### ◆ Pressure at Inlet

## ➤ Solution

### ◆ Analytic (Closed Form...)

### ◆ Resorting to Computers

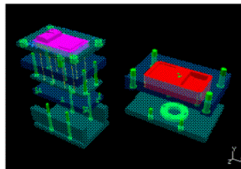
## ➤ Post-processing

### ◆ Trying to Make Sense of the Results

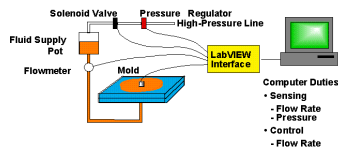
# LIMS GUI and Using LIMS



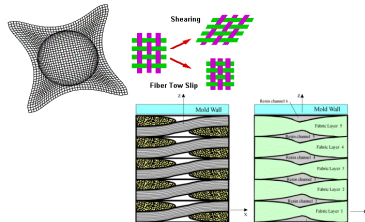
## Part Design/Meshing CAD Software



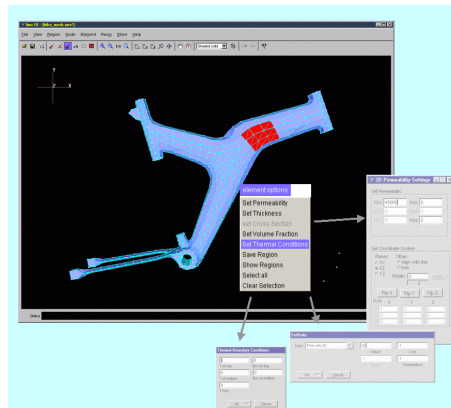
## Permeability Measurement



## Permeability and Preform Properties Computation PERM, DRAPE, ...



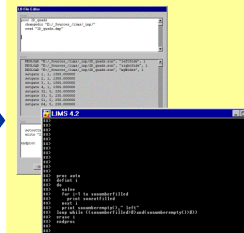
## Preparing Data for Simulation LIMS UI (User Interface)



- Converting Input Data
- Setting Material Properties
- Creating Gates and Vents
- Creating and Editing Control LBASICFiles

## Running Simulation LIMS or LIMSSLV

### Directly From LIMS UI

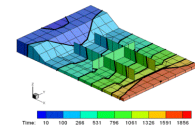


### From Command Line

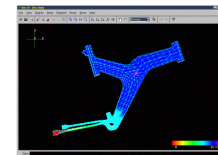
- Simulating Filling Procedure
- Executing Control Operations
- Writing Desired Output

## Post-processing Results LIMS UI, TECPLOT, ...

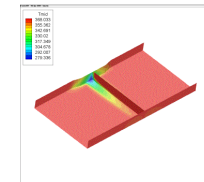
### Flow Patterns



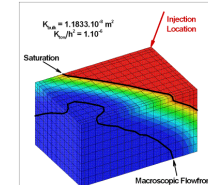
### Pressure



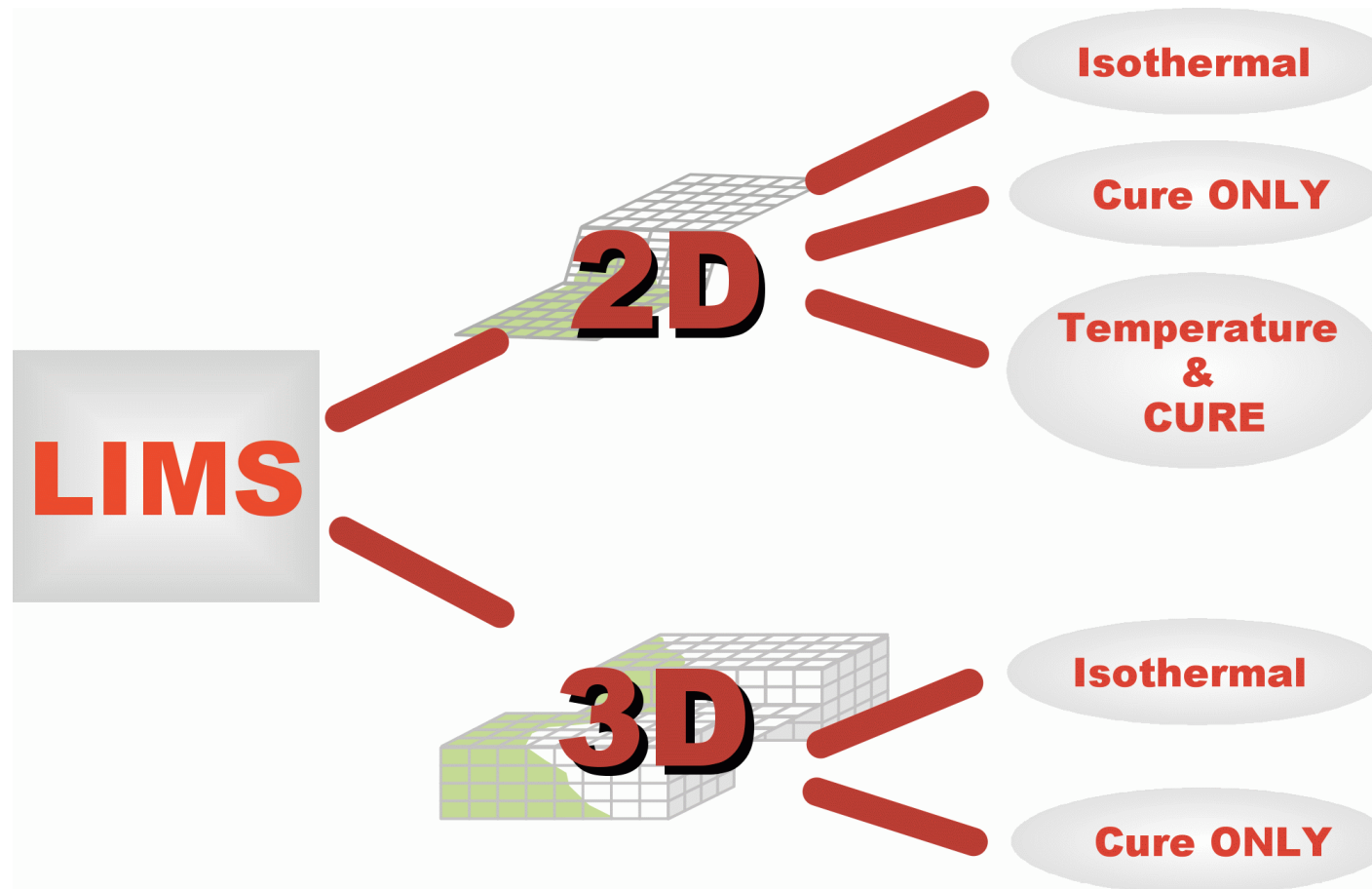
### Mid-plane Temperature



### Saturation



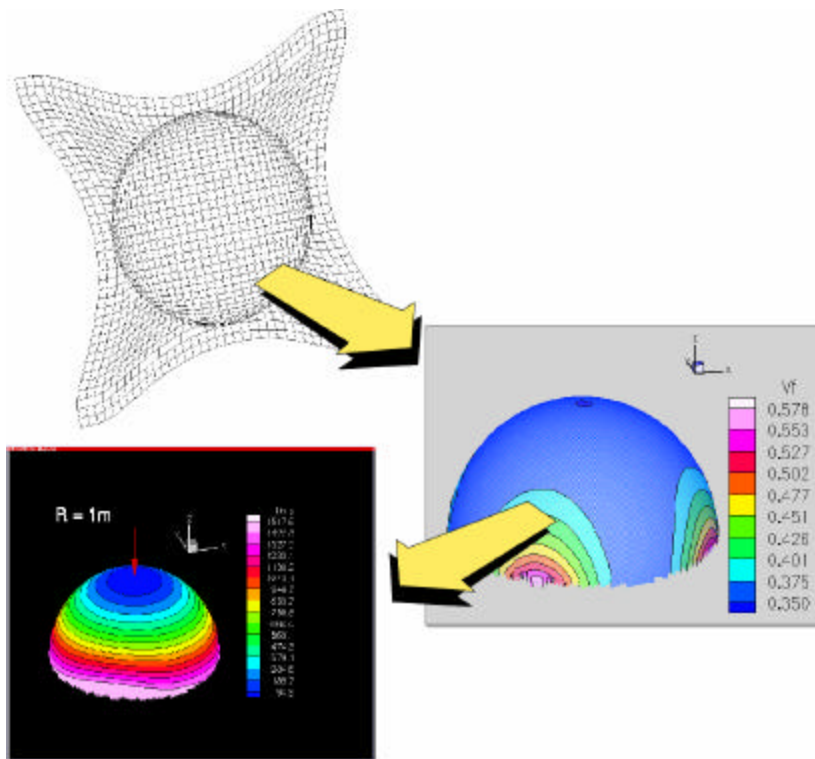
# Simulation Capabilities I



# Simulation Capabilities II



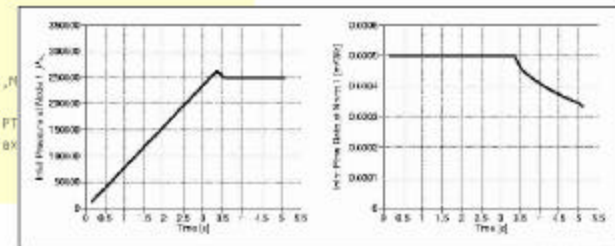
## Preform Deformation (Draping)



## Scripting Control

```
REM Procedure KGFILL is called to fill opened file
REM With KANAWI type gates of MaxP,MaxQ at nodes
REM given as
REM 3rd and further arguments
REM KGFILL MaxQ,MaxP,11,12 .... in
```

```
PROC KGFILL
  DEFINIT NoNodes,1
  DEFDBL MaxP,MaxQ
  LET MaxQ=ARGUMENT(1)
  LET MaxP=ARGUMENT(2)
  LET NoNodes=ARGC-2
  DIM Nd(NoNodes)
  FOR I=1 TO NoNodes
    LET Nd(I)=ARGUMENT(I+2)
    SETGATE (Nd(I),2,MaxQ)
  NEXT I
  DO
    SOLVE
    FOR I=1 TO NoNodes
      CALL KANBATE Nd(I),M
    NEXT I
    LOOP WHILE !SQNUMBEREMPT
    ERASE NoNodes,1,MaxP,MaxQ
  ENDPROC
```

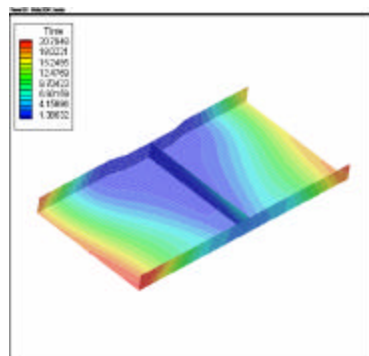




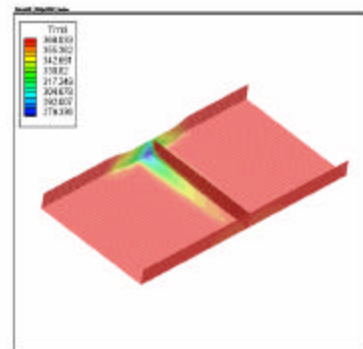
# Simulation Capabilities III



## Non-Isotropic Problems

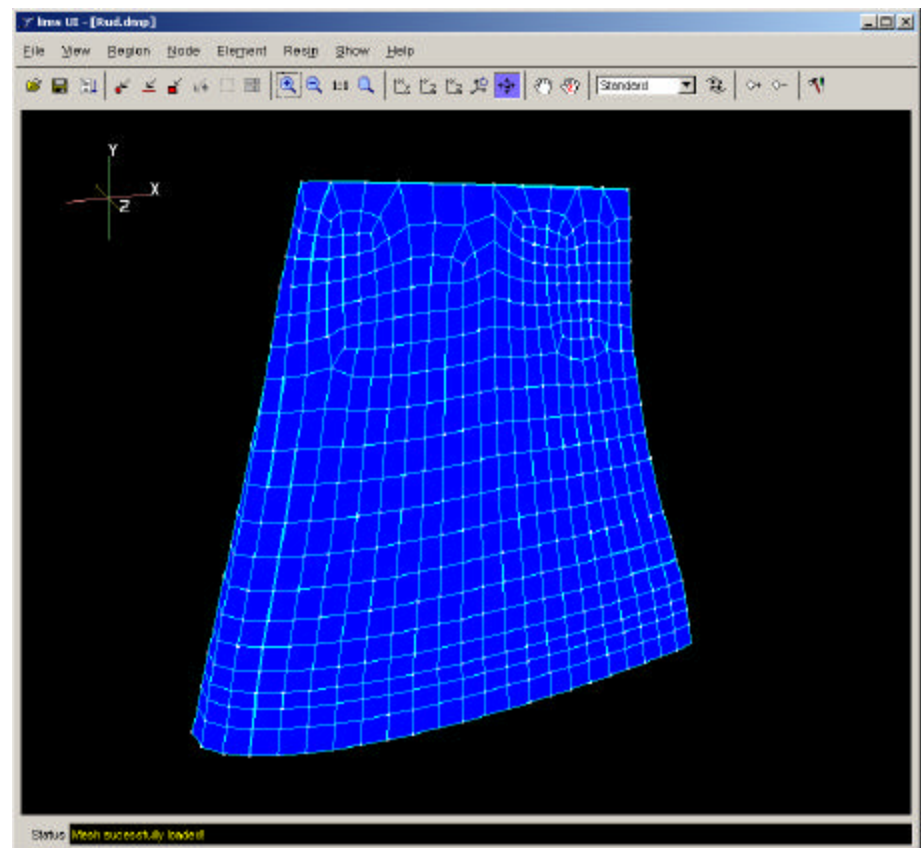


Flowfronts



Midplane temperature

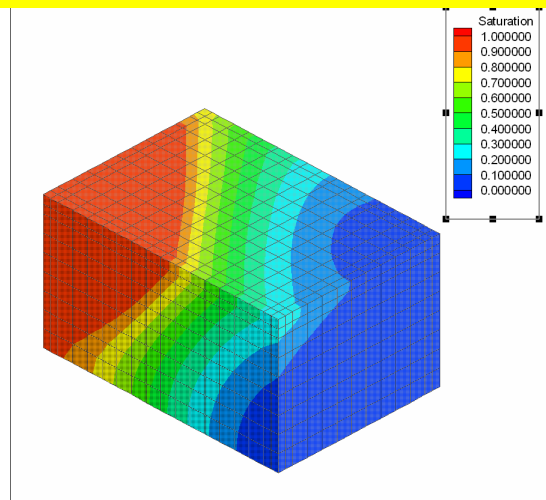
## Graphical User Interface



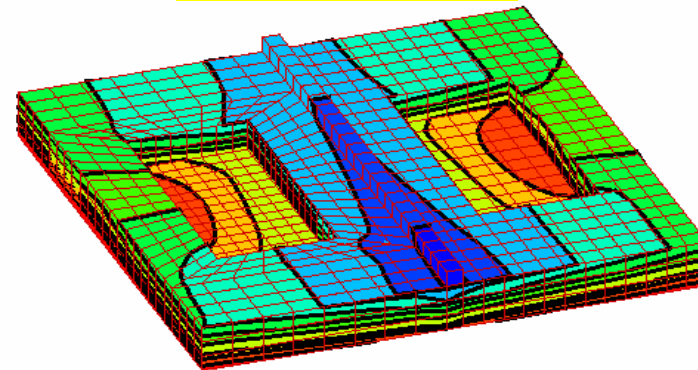
# Simulation Capabilities Examples



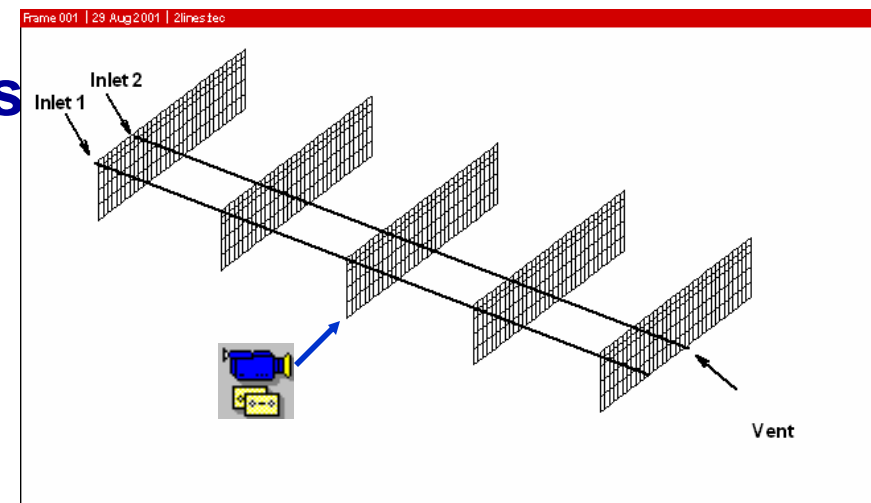
## Saturation of Tows



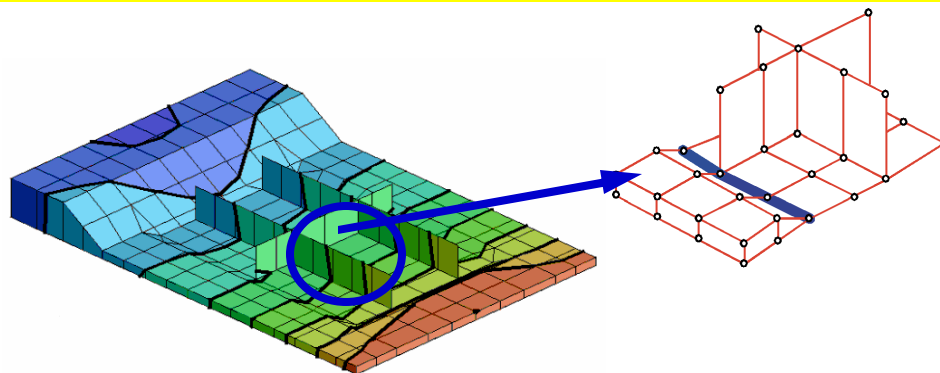
## FASTRAC



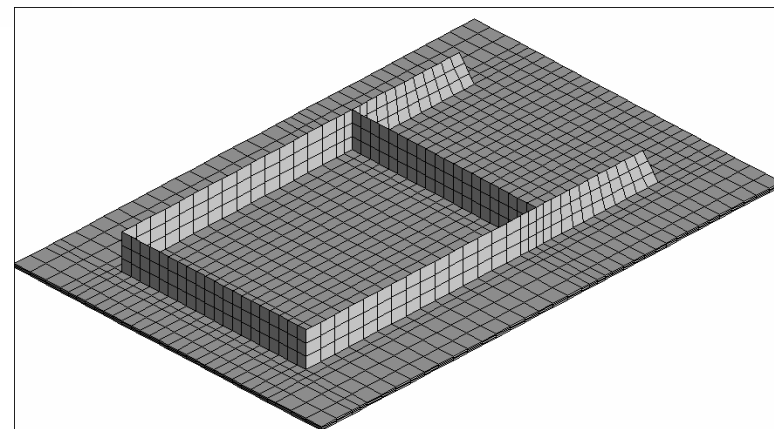
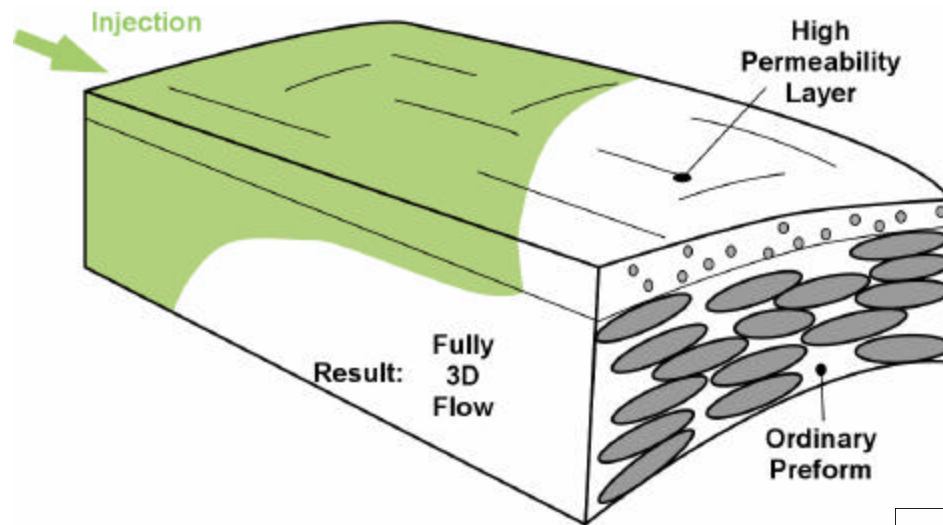
## Sequential VARTM Injection



## Integration of 2D and 3D elements

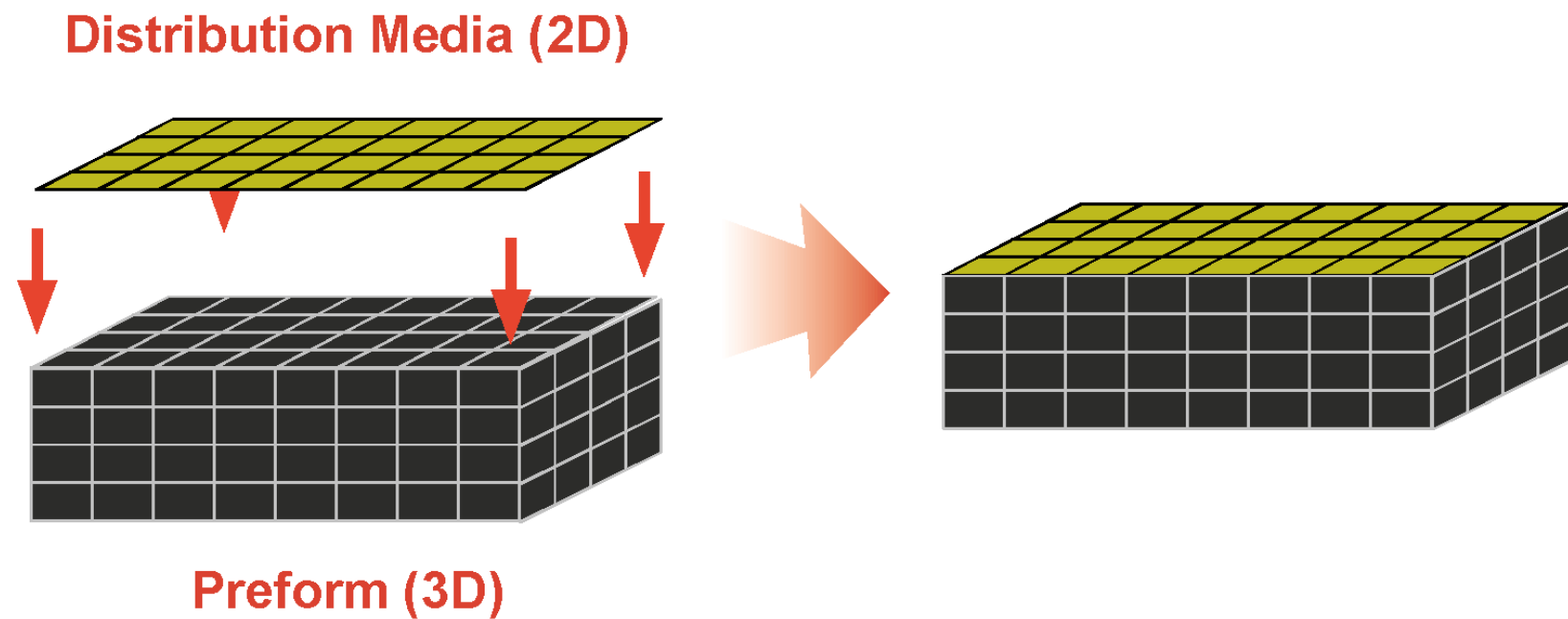


# Distribution Media Modeling

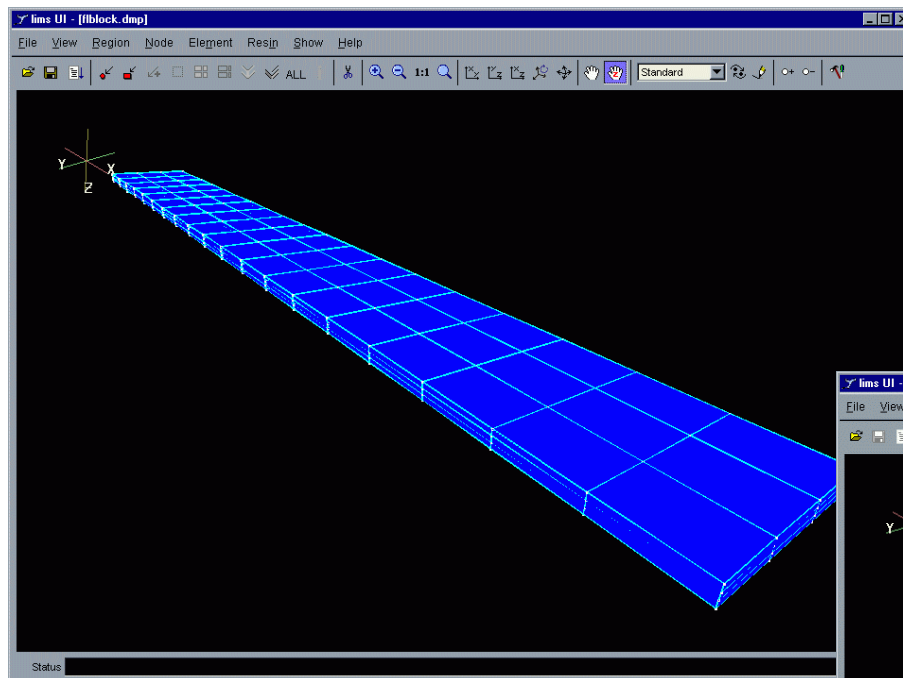




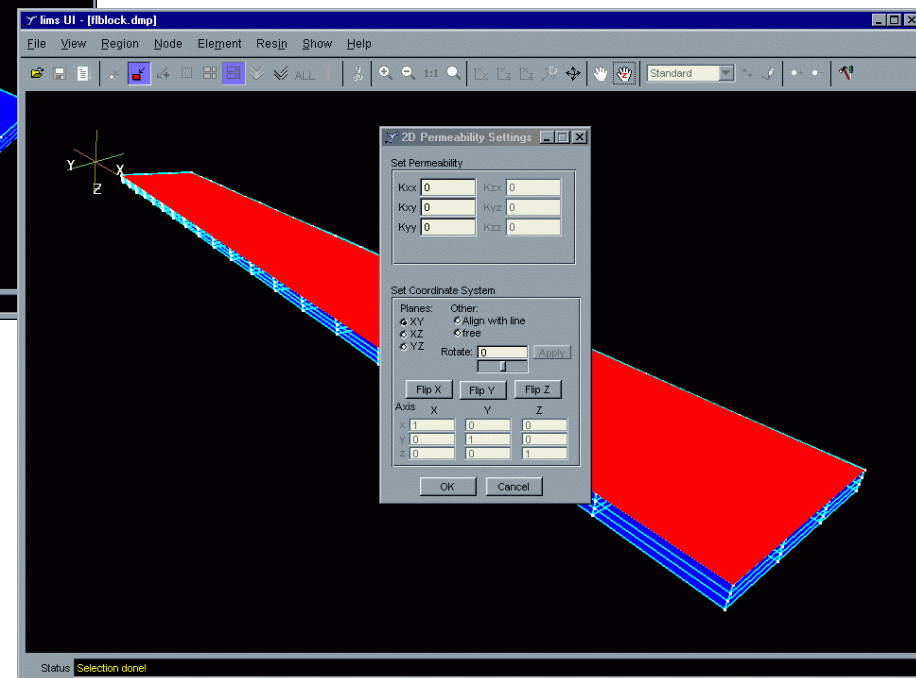
# Distribution Media Modeling I.



# Distribution Media Modeling II.



A few clicks later...



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# Lesson III. : Sensing and Control

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- **Is What Was Predicted Really Happening?**
  - ✦ **Not Sure! There May Be Various Disturbances**
- **Let's Check**
  - ✦ **Common Sense Feedback**
  - ✦ **Sensors and Sensing**
    - ✧ Flowfront Position
    - ✧ Pressure and Flowrate
    - ✧ Temperature
- **Never Test For an Error Condition You Cannot Handle: The Control**
  - ✦ **Multiple Injection Gates and Vents**
  - ✦ **Taking Control Action**

---

# Disturbances I

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## Where Do the Disturbances Come From ?

**Preform Deformation**

**Inaccurate Preform Cutting**

**Inaccurate Material Properties**

## How Do We Detect Disturbances ?

**When Process Fails**

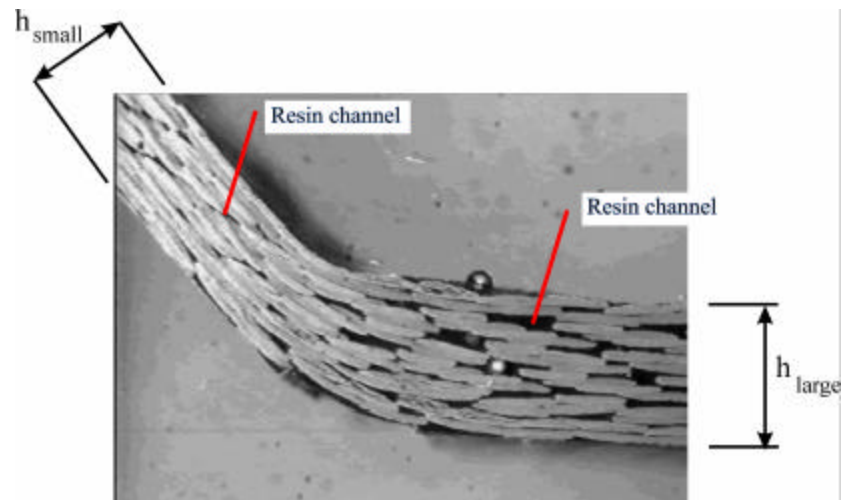
**When Part does not Pass Quality Control**

# Disturbances II



## How To Predict Possible Disturbances ?

Common Sense



Experience

Rules of Thumb

♦ Very Rare

# Sensors: How to Detect Disturbances



## ➤ Pointwise

## ➤ Lineal

◆ Electrical

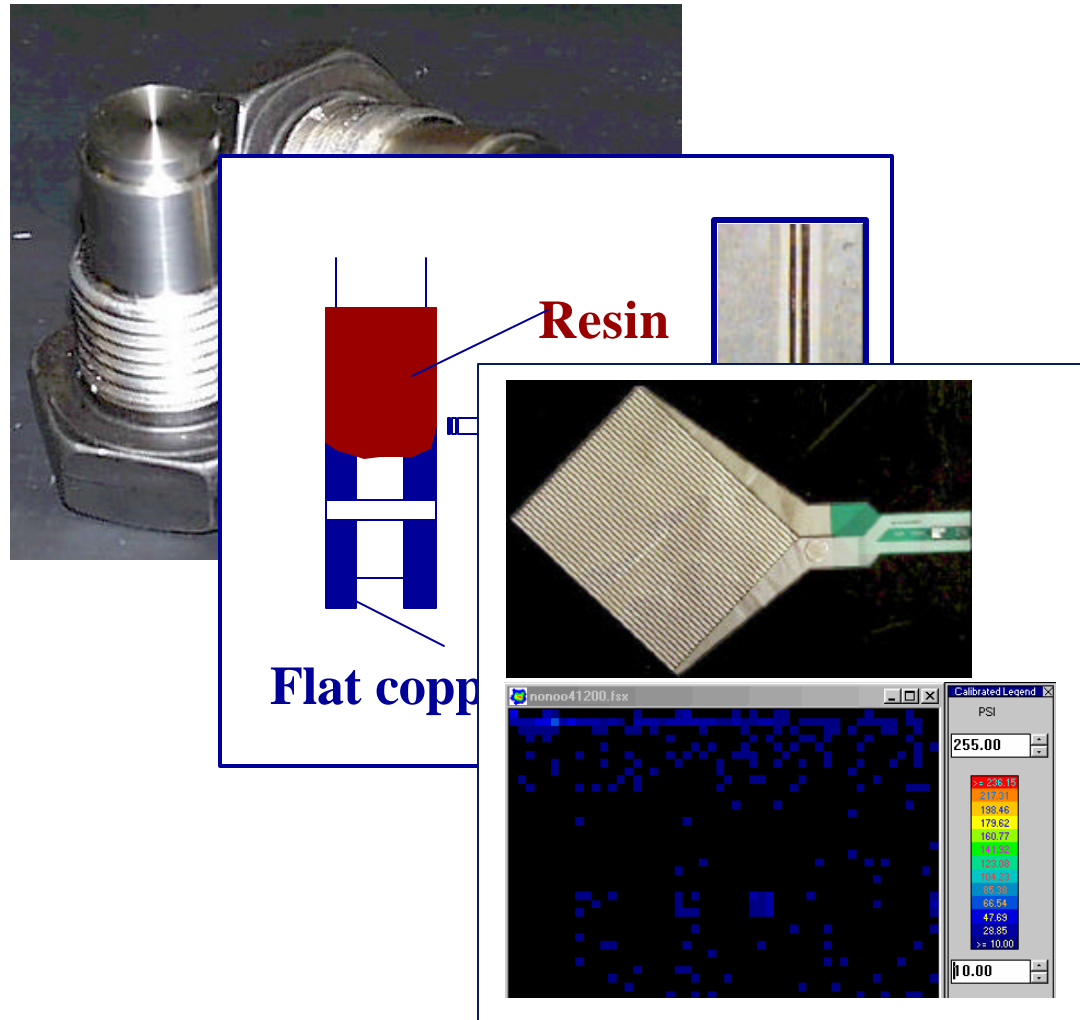
◆ Optical

## ➤ Visual Input

◆ Smartweave™

◆ Tekscan™

◆ Visual  
(Camera)



# Control Possibilities



## ➤ Possible:

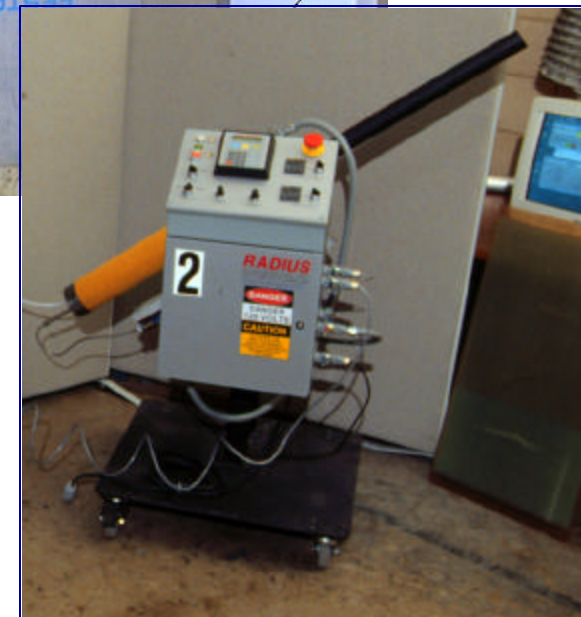
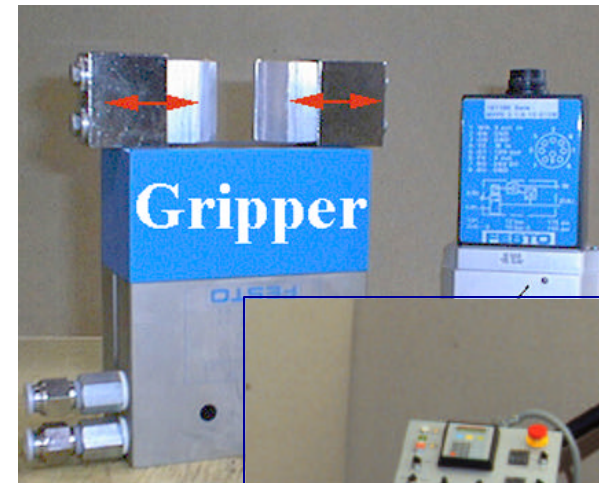
- ◆ Open/Close Gates
- ◆ Close Vents
- ◆ Control Pressure or Flow-Rate in Existing Gates
- ◆ Tinker with Injected Resin

## ➤ Barely Possible:

- ◆ Control Distribution Media
- ◆ Control Compaction

## ➤ Not Possible

- ◆ Tinker with Preform and Distribution Media Locations



# Can We Model the Disturbances and Sensors?



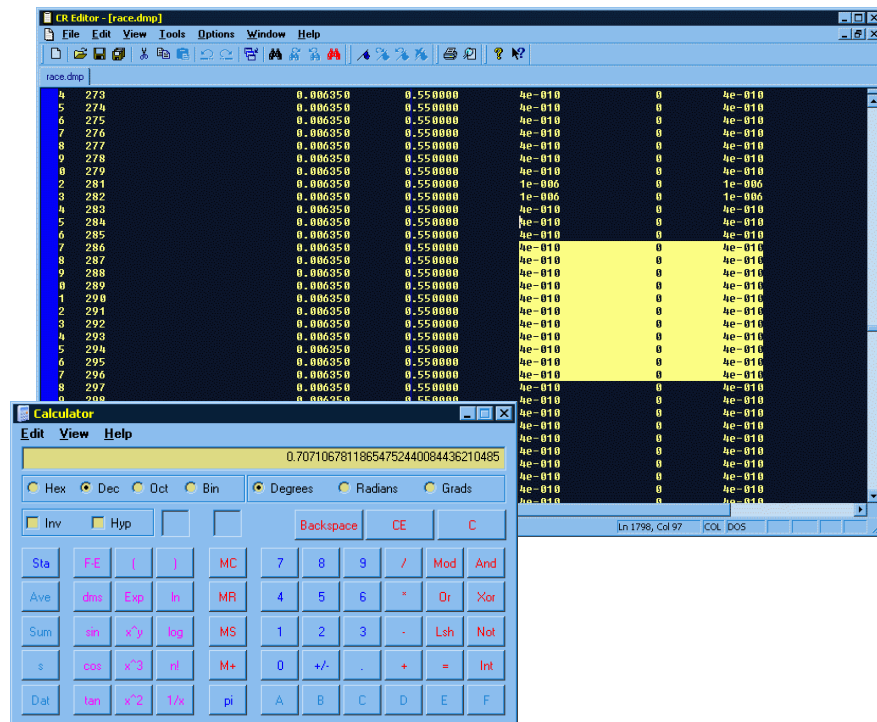
- **Variations in Resin Viscosity?**
  - ◆ **Yes, Primary Input Value**
- **Variations in Preform Permeability and Porosity?**
  - ◆ **As Above**
- **Racetracking Channels?**
  - ◆ **Multiple Options:**
    - ✧ High Permeability
    - ✧ 1D Elements
- **Sensor and Control Modeling**
  - ◆ **In LIMS One Can Access All the Data During Simulation and Change Settings Accordingly**



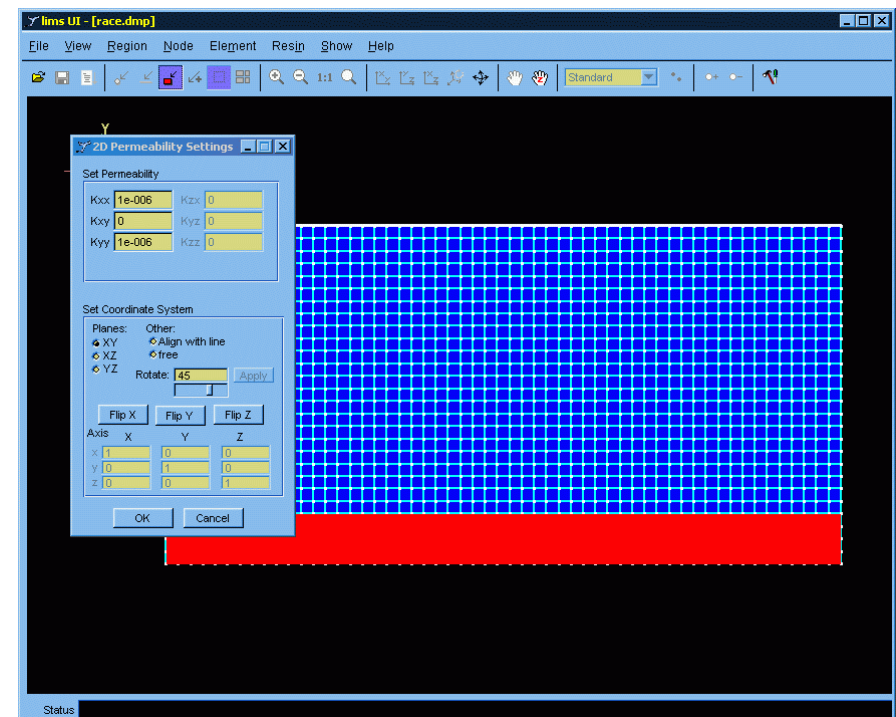
# LIMS UI - Changing Permeability



## LIMS Alone



## LIMS UI

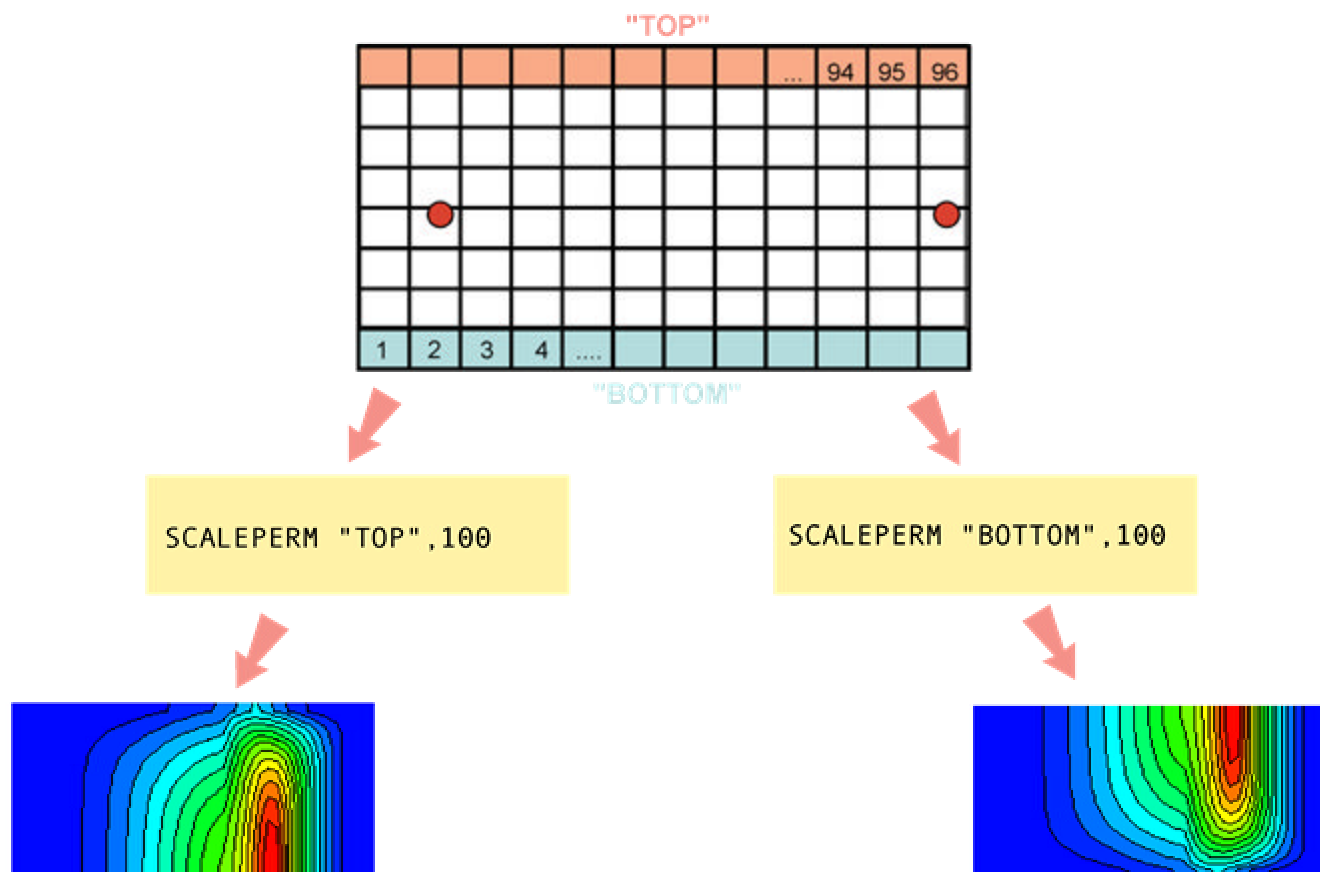


Hope you remember element numbers....

# Modeling Racetracking Channel I.



## Raise Permeability in Edge Elements!

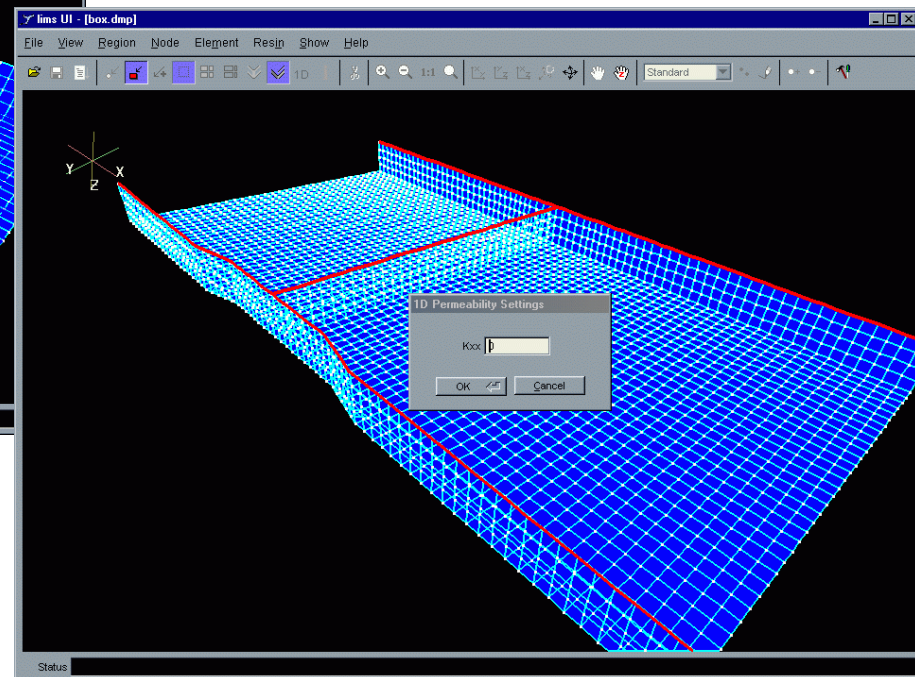
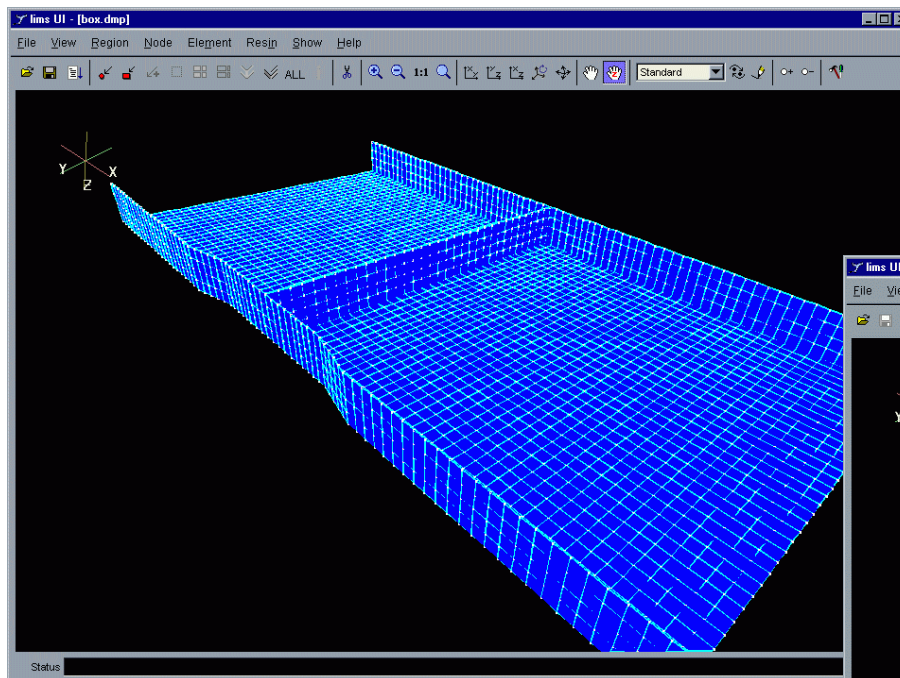


# Modeling Racetracking Channel II.

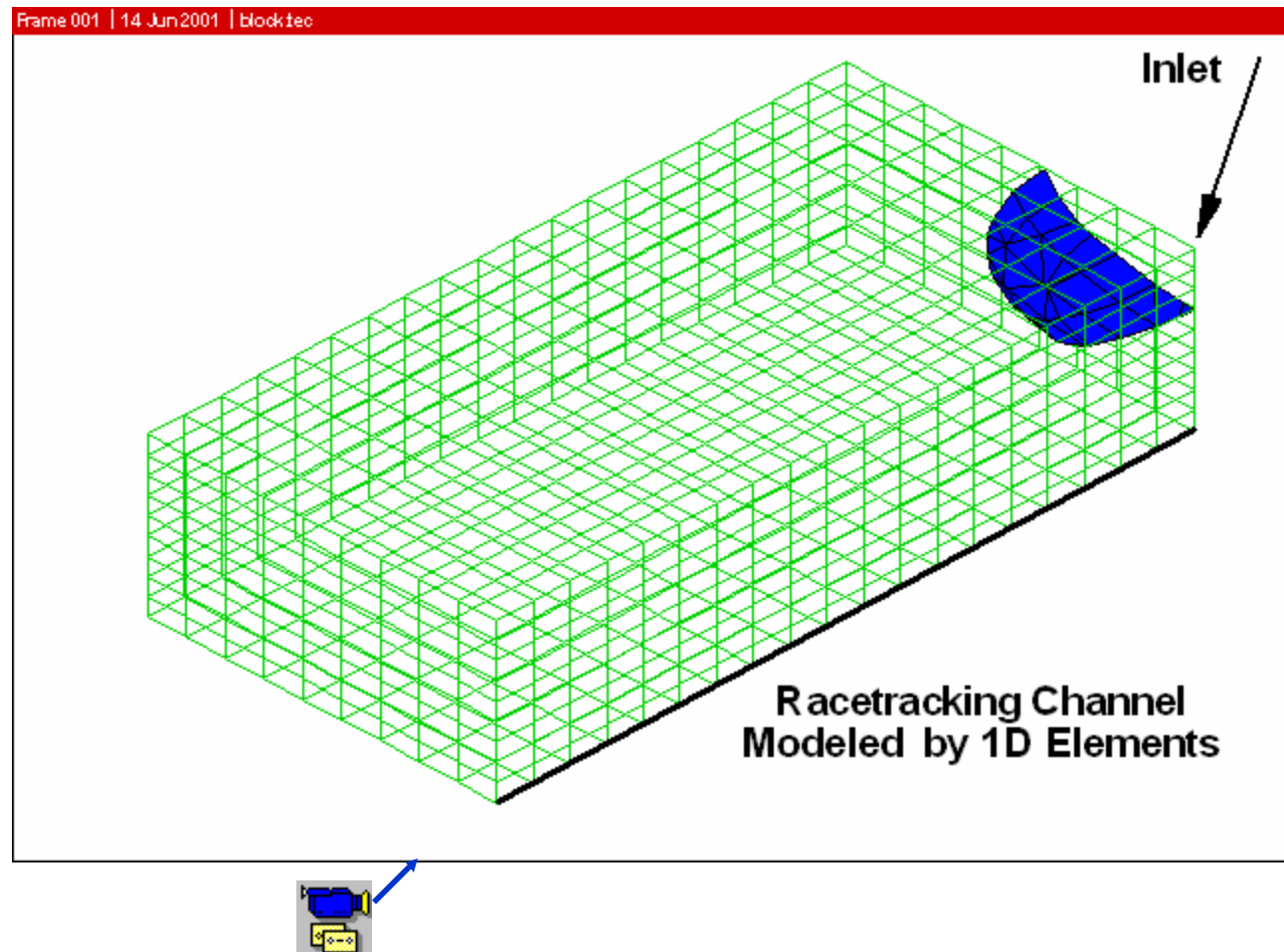


## Add 1D Elements!

A few clicks later...



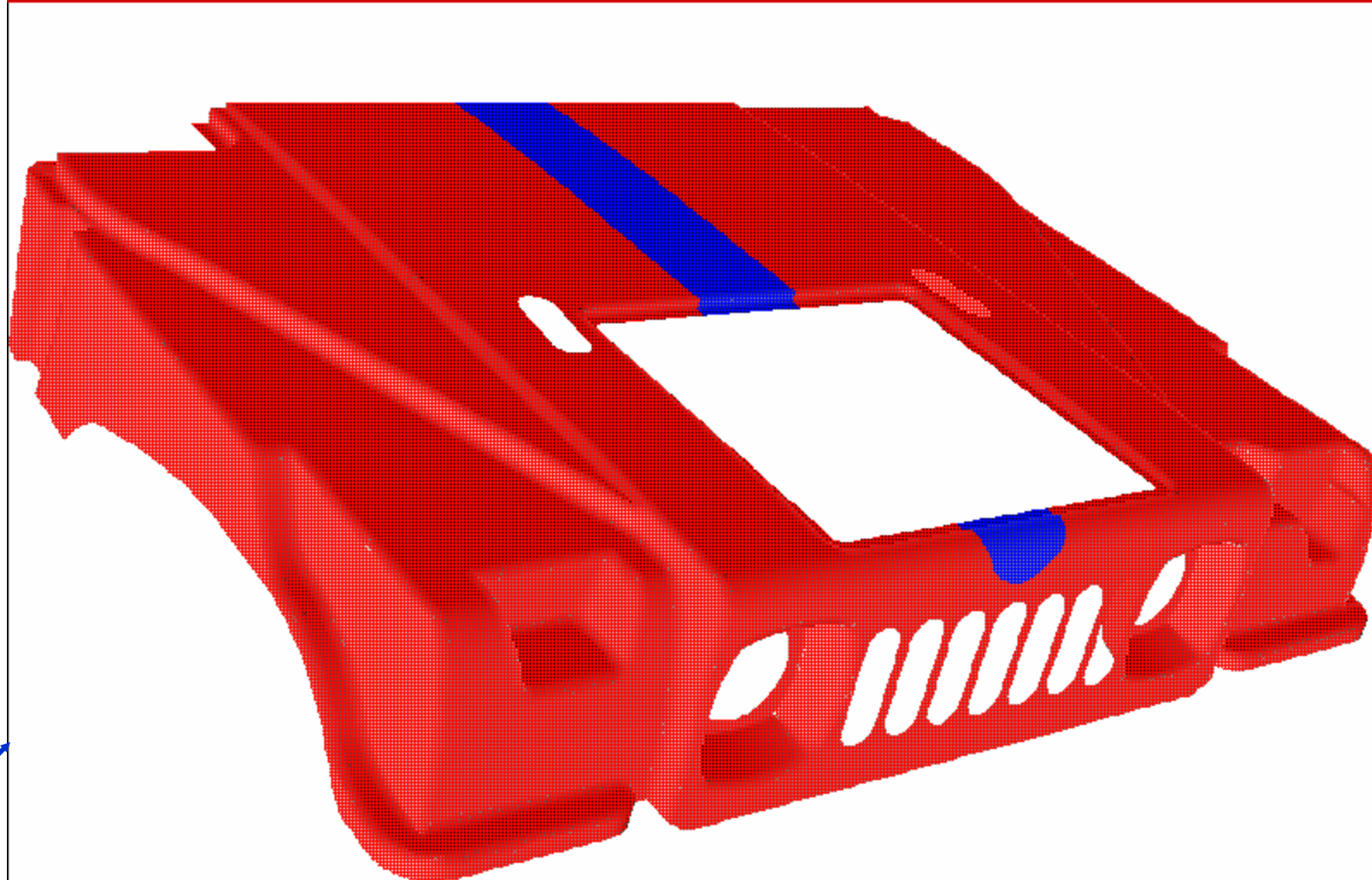
# 1D Elements for Racetracking



# Simple Adaptive Filling: Sensor Model



Frame 001 | 27 Jun 2002 | controlledfill.tec



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# Optimization

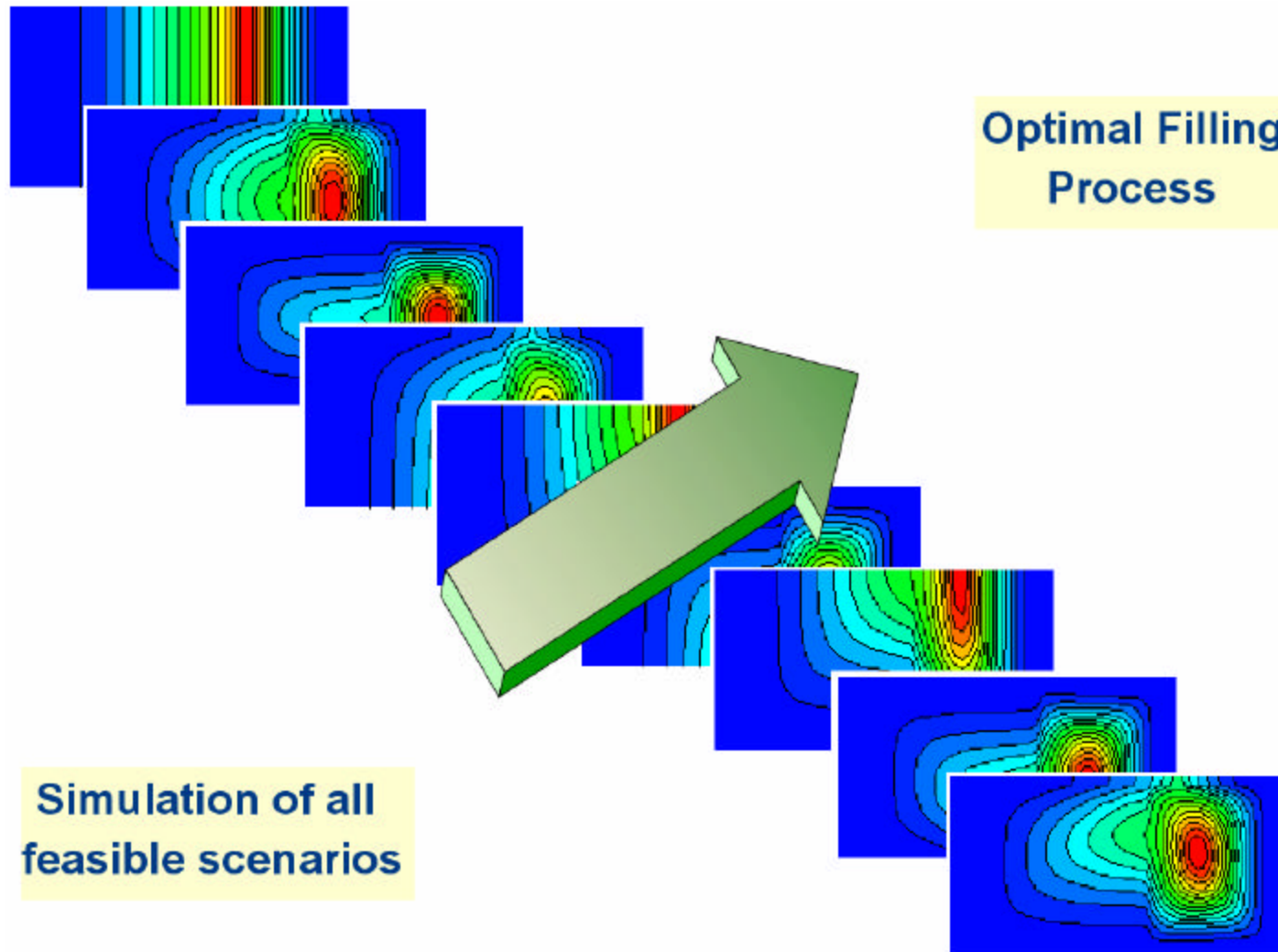
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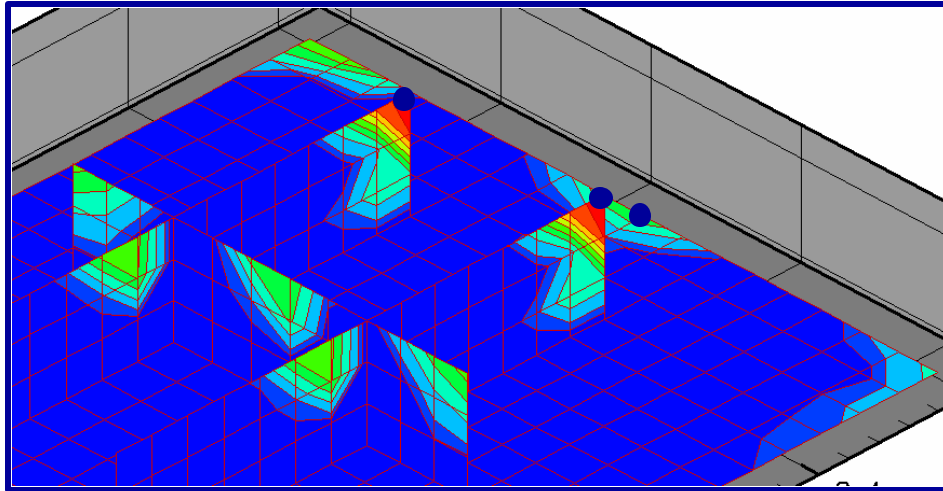
- **So Far We Just Tried to Make It**
- **The Real Challenge: How to make it Better**
- **What does Constitute “Better” (Cost Function) ?**
  - ◆ **Faster or Cheaper**
  - ◆ **Stronger or Better-Quality**
  - ◆ **Compromise between those Two**
- **What Can we Modify (Parameters)?**
  - ◆ **Part Design (Off-limits for Processing Only)**
  - ◆ **Material**
  - ◆ **Tooling and Process Parameters**
  - ◆ **Distribution Media**
- **How to Relate the Parameters to the Cost Function**
  - ◆ **!!! Efficiently !!!**



# Simple Optimization



# Optimal Auxiliary Vent Locations



## Cost Function:

Weighted average dry area size per each scenario

*Nominal case: 24.10*

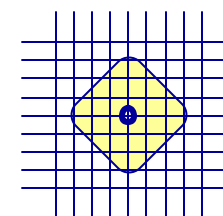
## Optimization Problem:

Given the number of auxiliary vents, find the vent configuration that will minimize the cost function.

## Tolerances:

A dry spot which include 3 or less nodes is ignored.

An area of radius 3 nodes around a vent is considered safe



# Optimal Auxiliary Vent Locations



## Given:

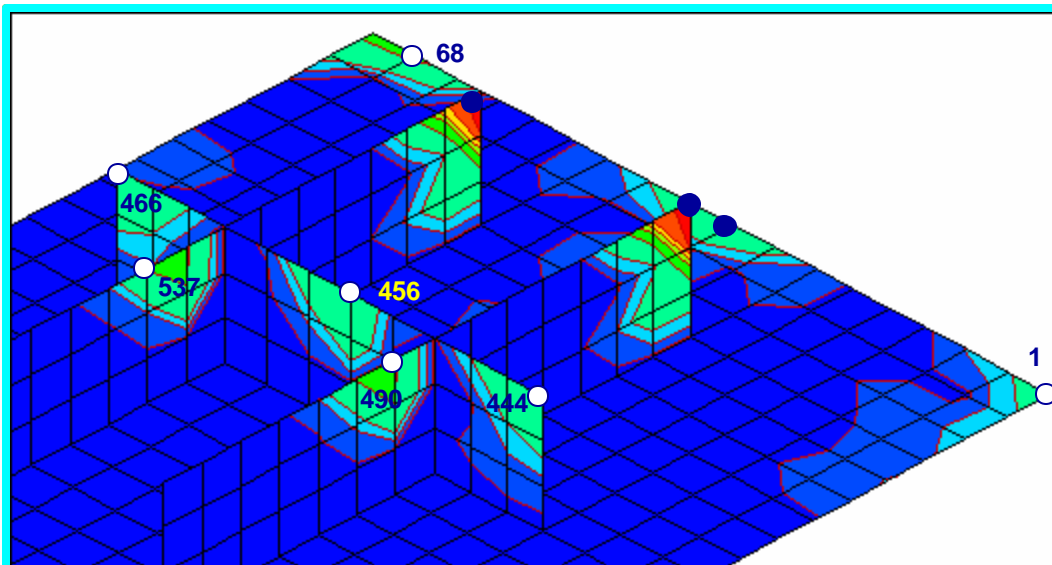
- Vend Candidate Pool
- Number of Auxiliary Vents

Permute Nodes in the Pool to obtain Vent Configurations

## Output:

- Optimal Vent Configurations

Apply Scenario Space to Each Vent Configuration and Estimate Cost Function



## Exhaustive Search

- 551 nodes in the candidate pool
- 151,525 possibilities for 2 auxiliary vents

## Exhaustive Search II:

- 104 nodes in the candidate pool
- 5,356 possibilities for 2 auxiliary vents

## Exhaustive Search III:

- 7 nodes in the candidate pool
- 21 possibilities for 2 auxiliary vents

# Results, 2-Vent Configurations



## Exhaustive Search II

5,356 vent configurations

Best Aux. Vent Configuration  
*Vents @ nodes [1 72]*

Cost function: 16.4

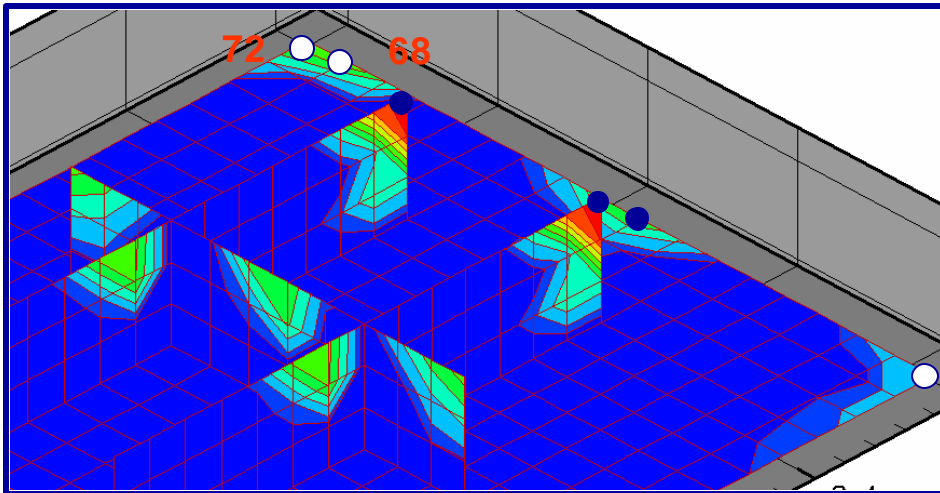
## Exhaustive Search III

21 vent configurations

Best Aux. Vent Configuration  
*[68 1] numbered nodes*

Cost function: 17.4

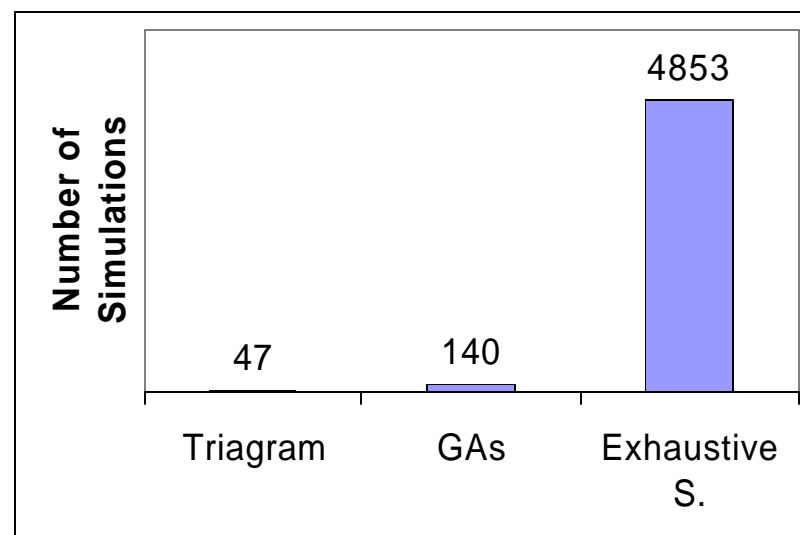
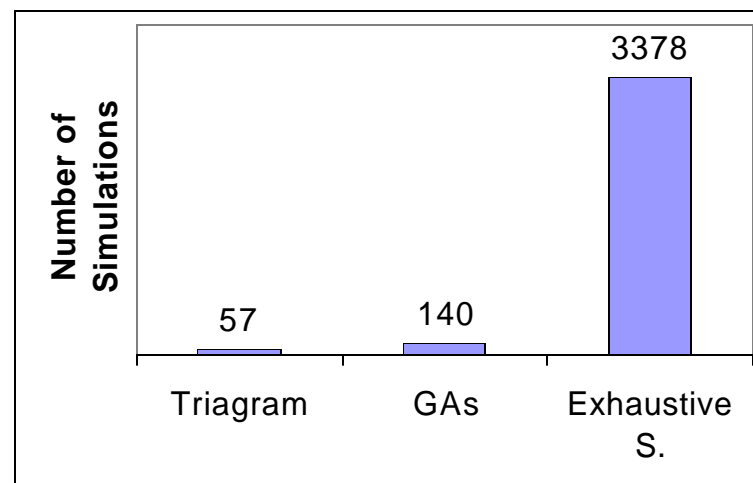
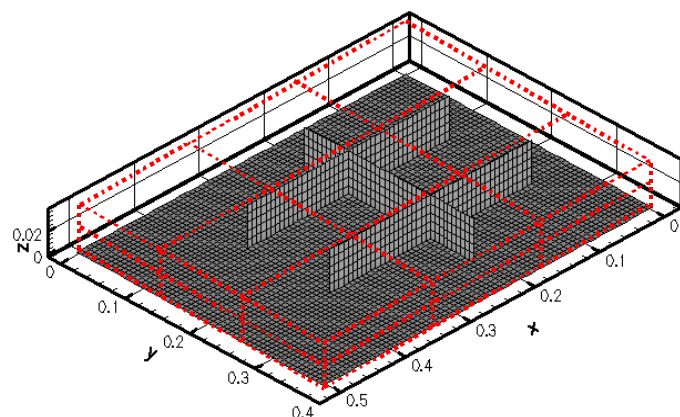
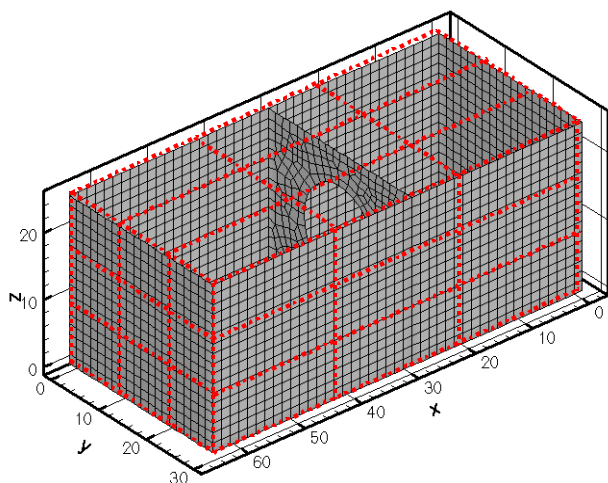
neighbors



Accuracy loss: 6.1 %

Computational  
Savings: 99.6 %

# Optimization of Fill Time: The Quest for Effectiveness

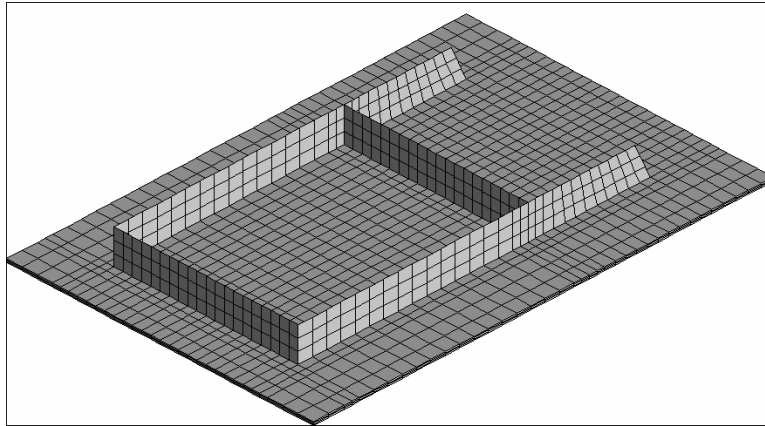




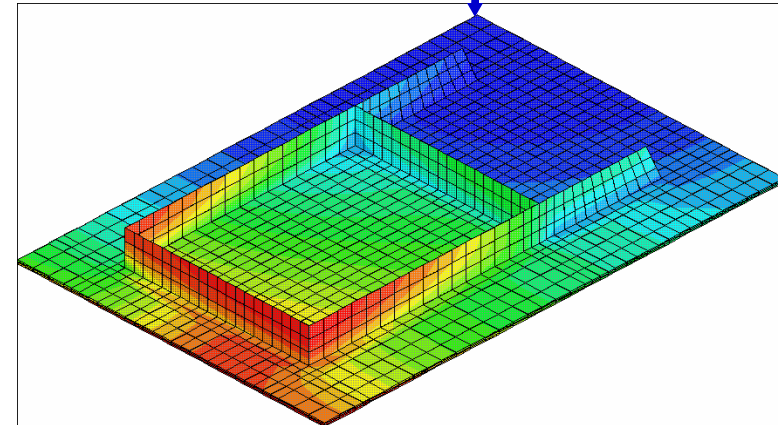
# Optimization: “Distribution” of Distribution Media



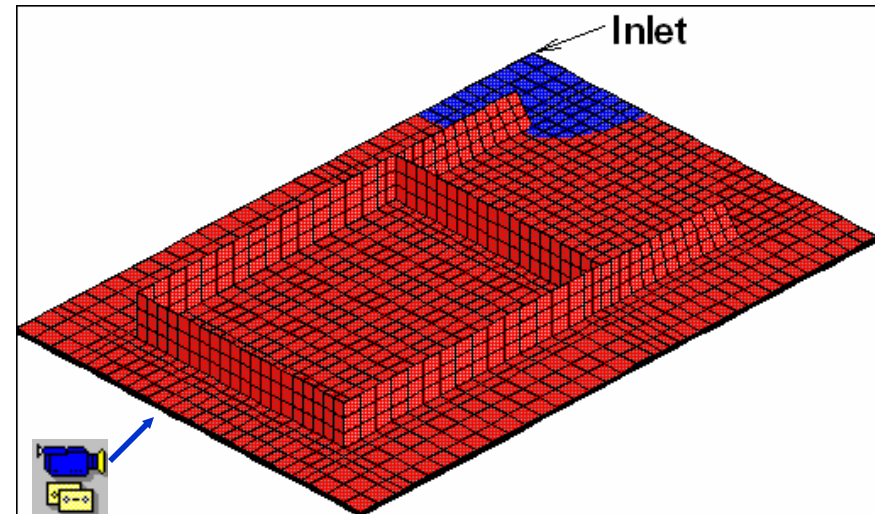
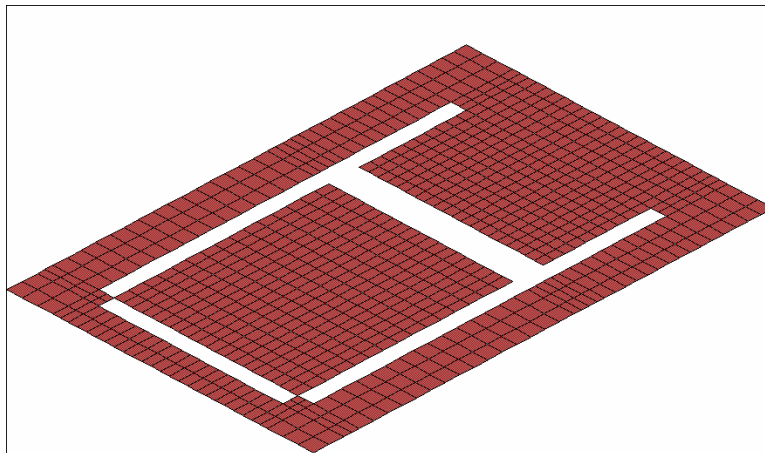
Part



Flowfronts

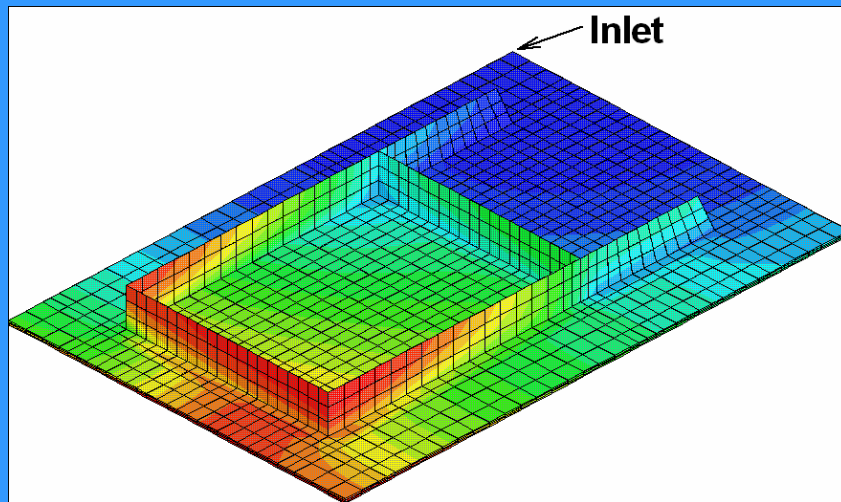


Distribution Media





# Can We Expect Any Problems?



Original Preform Permeability

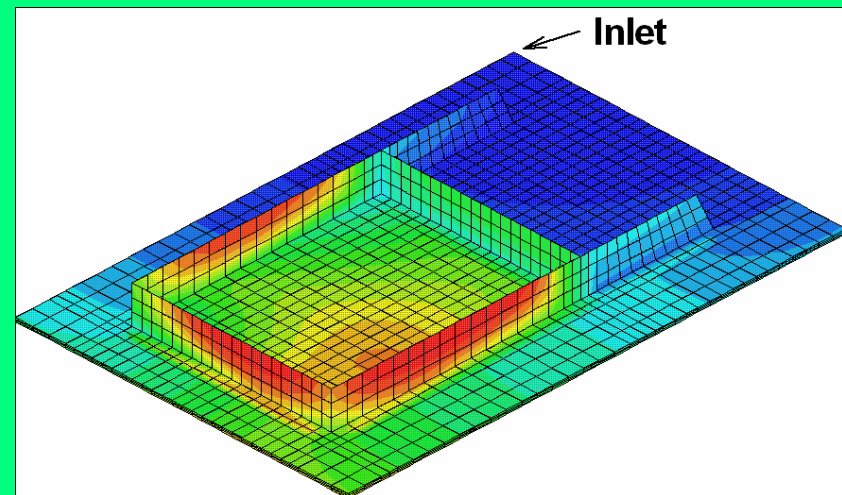
$$K_{\text{bulk}} = 1.10^{-10}$$

$$K_{\text{DM}} = 1.10^{-8}$$

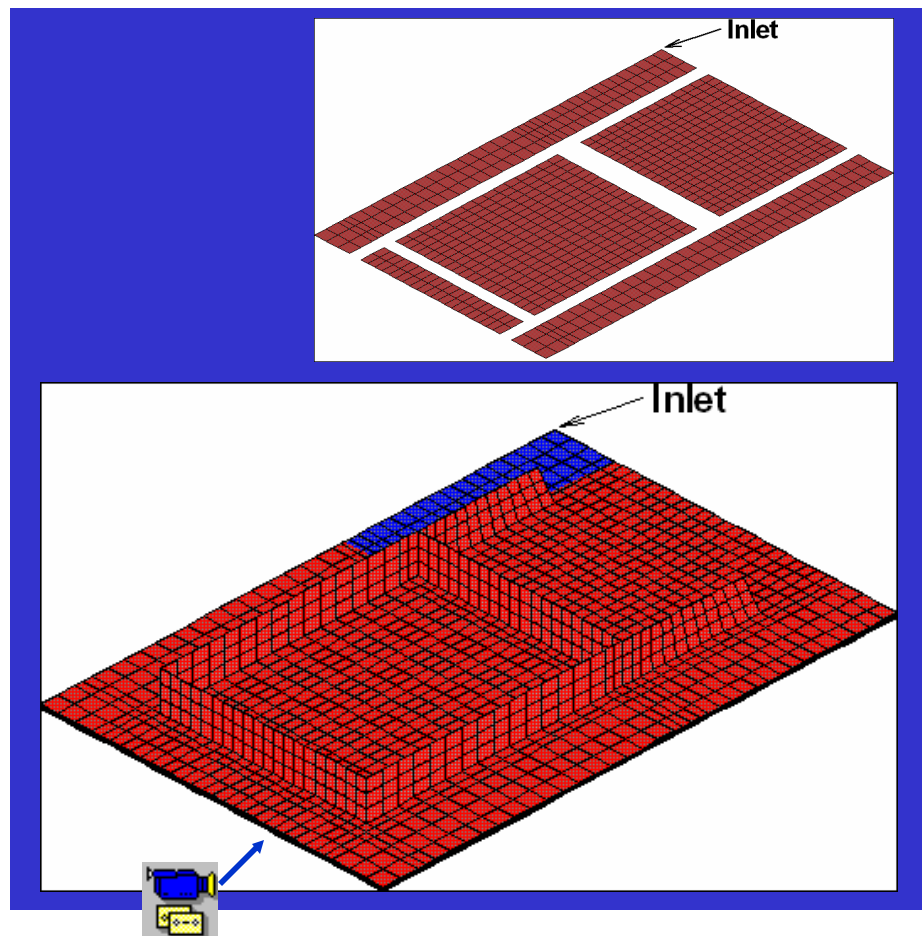
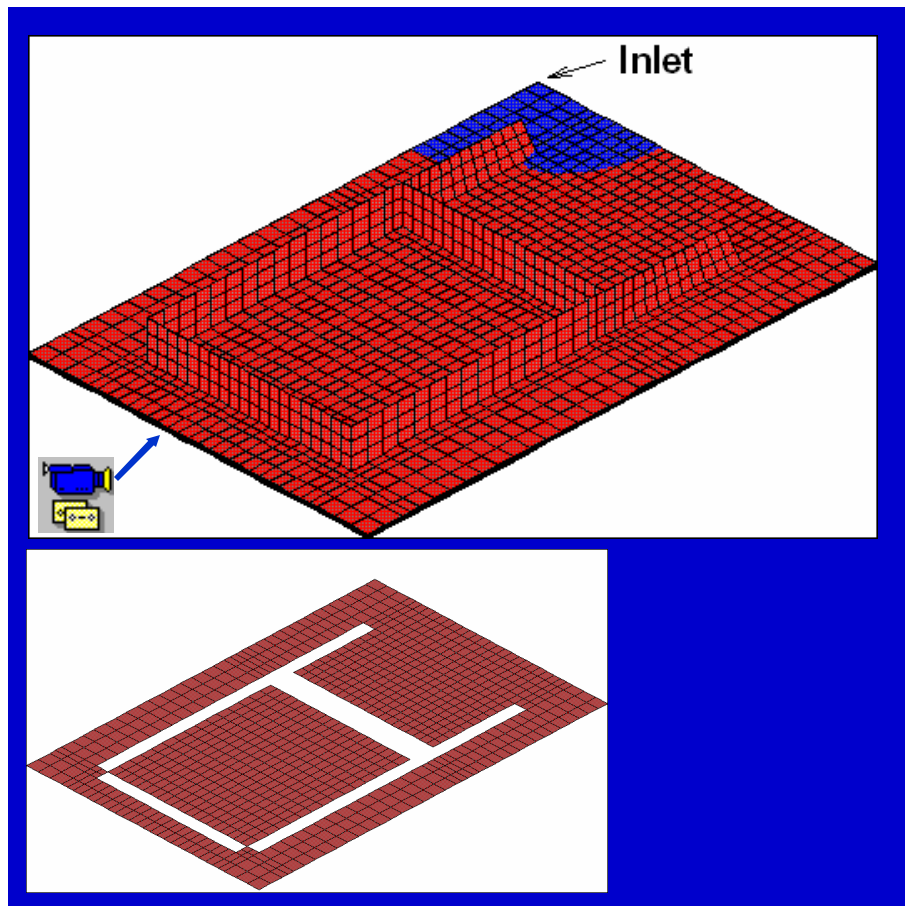
Reduced Preform Permeability

$$K_{\text{bulk}} = 1.10^{-11}$$

$$K_{\text{DM}} = 1.10^{-8}$$



# Can We Help It?



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# Conclusions I.

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- **Filling Process Can Be Accurately Simulated**
- **Tools Are Readily Available**
- **Simulation Allows Design of Process without Expensive Trial-and-Error Stage.**
- **Process Control and Optimization Require Flexible Simulation Tools**
  - ◆ **Repetitive Virtual Processes are Required**
- **It Is Possible to Deal with Process Disturbances via Automated Control**
  - ◆ **Simulation is Necessary for Design of Non-trivial Process Control**
- **It is Possible to Optimize Process Design With Respect to Various Cost Functions**
  - ◆ **Simulation is Necessary for Non-trivial Cases**

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## Conclusions II.

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- **Simulation Tools Depend on Experimental Methods (or Additional Simulation) for Input Data**
  - ◆ **Permeability Components**
  - ◆ **Also Resin Data, Porosity, etc.**
- **Simulation, Optimization and Control Require Occasional Experimental Verification**
- **User Expertise Is Still Important**
  - ◆ **Building Part Model(s)**
  - ◆ **Prediction of Possible Disturbances**
  - ◆ **Dealing with Cost Functions**

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# Credits

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**Dr. K.T. Hsiao**  
**Nuno Correia**  
**Jeffrey Acheson**  
**Jeffrey Lawrence**  
**Dhiren Modi**  
**Christof Ledermann**  
**Steffen Schulze**  
**Kai Broszat**  
**Jost F. Neumann**  
**Mark Schlieker**

**Mathieu Devillard**  
**Ali Gokce**  
**Hubert Stadfeld**  
**Mathias Behrens**  
**Swen Elpelt**  
**Angelika Geyer**  
**Yeshwanth Rao**  
**Ben Lenhard**  
**And others....**